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# **14-BITS, 125/105/80/65 MSPS ADC WITH DDR LVDS/CMOS OUTPUTS**

## **<sup>1</sup>FEATURES**

- •**Maximum Sample Rate: 125 MSPS**
- **14-Bit Resolution with No Missing Codes**
- • **3.5 dB Coarse Gain and up to 6 dB Programmable Fine Gain for SNR/SFDR Trade-Off**
- Parallel CMOS and Double Data Rate (DDR)
- **Supports Sine, LVCMOS, LVPECL, LVDS Clock** buffer help to achieve high SNR and high SFDR even **Inputs, and Clock Amplitude Down to 400 mV<sub>PP</sub>** The ADS614X feature coarse and fine gain options to
- •
- **Internal Reference with Support for External**
- • **No External Decoupling Required for References**
- • **Programmable Output Clock Position and Drive Strength to Ease Data Capture programmability.**
- •**3.3-V Analog and 1.8-V to 3.3-V Digital Supply**
- •
- 

## **APPLICATIONS**

- 
- •
- •**Power Amplifier Linearization**
- •**802.16d/e**
- •**Test and Measurement Instrumentation**
- •**High Definition Video**
- •**Medical Imaging**

#### • **Radar Systems**

## **DESCRIPTION**

ADS6145/ADS6144/ADS6143/ADS6142 (ADS614X) are <sup>a</sup> family of 14-bit A/D converters with sampling frequencies up to 125 MSPS. The high performance and low power consumption of the ADS614X are **Parallel CMOS and Double Data Rate (DDR)** combined in <sup>a</sup> compact <sup>32</sup> QFN package. An internal high bandwidth sample and hold and a low jitter clock<br>buffer help to achieve high SNR and high SFDR even at high input frequencies.

**Clock Duty Cycle Stabilizer** improve SFDR performance at lower full-scale analog input ranges.

**Reference** The digital data outputs are either parallel CMOS or DDR (Double Data Rate) LVDS. Several features exist to ease data capture such as — controls for output clock position and output buffer drive strength,<br>LVDS current. and internal termination current, and internal termination

The output interface type, gain, and other functions **32-QFN Package (5 mm × 5 mm)** are programmed using a 3-wire serial interface. **Pin Compatible 12-Bit Family (ADS612X) Alternatively, some functions are configured using** dedicated parallel pins so the device powers up to the desired state.

**Wireless Communications Infrastructure** The ADS614X include internal references while **Software Defined Radio Exercise 2 and 2** eliminating traditional reference pins and associated external decoupling. External reference mode is also supported.

> The ADS614X are specified over the industrial temperature range  $(-40^{\circ}$ C to 85°C).



#### **ADS614X Performance Summary**



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

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This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.



#### **ADS61XX FAMILY**



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## **PACKAGE/ORDERING INFORMATION(1)**



(1) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at [www.ti.com](http://www.ti.com).

(2) For thermal pad size on the package, see the mechanical drawings at the end of this data sheet.  $\theta_{JA} = 34 \degree C/W$  (0 LFM air flow),  $\theta_{\text{JC}}$  = 30 °C/W when used with 2 oz. copper trace and pad soldered directly to a JEDEC standard four layer 3 in × 3 in (7.62 cm × 7.62 cm) PCB.

## **ABSOLUTE MAXIMUM RATINGS(1)**



(1) Stresses beyond those listed under *absolute maximum ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *recommended operating conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

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## **RECOMMENDED OPERATING CONDITIONS**

over operating free-air temperature range (unless otherwise noted)



(1) For easy migration to next generation, higher sampling speed devices (> 125 MSPS), use 1.8V DRVDD supply.

(2) See *Output Buffer Strength [Programmability](#page-49-0)* in the application section.

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## **ELECTRICAL CHARACTERISTICS**

Typical values are at 25°C, min and max values are across the full temperature range T<sub>MIN</sub> = –40°C to T<sub>MAX</sub> = 85°C, AVDD = DRVDD <sup>=</sup> 3.3 V, maximum rated sampling frequency, 50% clock duty cycle, –1 dBFS differential analog input, internal reference mode, applies to CMOS and LVDS interfaces, unless otherwise noted.



(1) Specified by design and characterization; not tested in production.

(2) In CMOS mode, the DRVDD current scales with the sampling frequency and the load capacitance on the output pins (see **[Figure](#page-37-0) 87**). The maximum DRVDD current depends on the actual load capacitance on the digital output lines. Note that the maximum recommended load capacitance is 10 pF.

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## **ELECTRICAL CHARACTERISTICS**

Typical values are at 25°C, min and max values are across the full temperature range T<sub>MIN</sub> = –40°C to T<sub>MAX</sub> = 85°C, AVDD = DRVDD <sup>=</sup> 3.3 V, maximum rated sampling frequency, 50% clock duty cycle, –1 dBFS differential analog input, internal reference mode, applies to CMOS and LVDS interfaces, unless otherwise noted.



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**ELECTRICAL CHARACTERISTICS (continued)**

Typical values are at 25°C, min and max values are across the full temperature range T<sub>MIN</sub> = –40°C to T<sub>MAX</sub> = 85°C, AVDD = DRVDD <sup>=</sup> 3.3 V, maximum rated sampling frequency, 50% clock duty cycle, –1 dBFS differential analog input, internal reference mode, applies to CMOS and LVDS interfaces, unless otherwise noted.



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## **DIGITAL CHARACTERISTICS(1)**

The dc specifications refer to the condition where the digital outputs are not switching, but are permanently at <sup>a</sup> valid logic level 0 or 1,  $AVDD = 3.3 V$ 



(1) All LVDS and CMOS specifications are characterized, but not tested at production.

 $(2)$  SCLK and SEN function as digital input pins when they are used for serial interface programming. When used as parallel control pins, analog voltage needs to be applied as per [Table](#page-11-0) 1 & [Table](#page-11-0) 2

(3) I<sub>O</sub> Refers to the LVDS buffer current setting,  $R_L$  is the differential load resistance between the LVDS output pair.



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## **TIMING CHARACTERISTICS – LVDS AND CMOS MODES(1)**

Typical values are at 25°C, min and max values are across the full temperature range  $T_{MIN} = -40$ °C to  $T_{MAX} = 85$ °C, AVDD = DRVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock, 1.5 V<sub>PP</sub> clock amplitude, C<sub>L</sub> = 5 pF<sup>(2)</sup>, l<sub>O</sub> = 3.5 mA, R<sub>L</sub> = 100 Ω <sup>(3)</sup>, no internal termination, unless otherwise noted.

For timings at lower sampling frequencies, see section Output [Timings](#page-53-0) in the APPLICATION INFORMATION of this data sheet.



(1) Timing parameters are specified by design and characterization and not tested in production.

 $(2)$   $C_L$  is the Effective external single-ended load capacitance between each output pin and ground.

(3)  $I_0$  Refers to the LVDS buffer current setting; R<sub>i</sub> is the differential load resistance between the LVDS output pair.

(4) Measurements are done with a transmission line of 100 Ω characteristic impedance between the device and the load.<br>(5) Setup and hold time specifications take into account the effect of jitter on the output data and c

Setup and hold time specifications take into account the effect of jitter on the output data and clock.

(6) Data valid refers to <sup>a</sup> logic high of +100 mV and logic low of –100 mV.

(7) For DRVDD <sup>&</sup>lt; 2.2 V, it is recommended to use an external clock for data capture and NOT the device output clock signal (CLKOUT). See *Parallel CMOS [interface](#page-49-0)* in the application section.

(8) Data valid refers to a logic high of 2 V (1.7 V) and logic low of 0.8 V (0.7 V) for DRVDD = 3.3 V (2.5 V).

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## **TIMING CHARACTERISTICS – LVDS AND CMOS MODES (continued)**

For timings at lower sampling frequencies, see section Output [Timings](#page-53-0) in the APPLICATION INFORMATION of this data sheet.



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#### <span id="page-11-0"></span>**DEVICE PROGRAMMING MODES**

The ADS614X have several features that can be easily configured using either parallel interface control or serial interface programming.

#### **USING SERIAL INTERFACE PROGRAMMING ONLY**

To program using the serial interface, the internal registers must first be reset to their default values, and the RESET pin must be kept *low*. In this mode, SEN, SDATA, and SCLK function as serial interface pins and are used to access the internal registers of the ADC. The registers are reset either by applying <sup>a</sup> pulse on the RESET pin or by <sup>a</sup> *high* setting on the <RST> bit (D4 in register 0x00). The Serial [Interface](#page-12-0) section describes register programming and register reset in more detail.

#### **USING PARALLEL INTERFACE CONTROL ONLY**

To control the device using the parallel interface, keep RESET tied *high* (AVDD). Now SEN, SCLK, SDATA, and PDN function as parallel interface control pins. These pins can be used to directly control certain modes of the ADC by connecting them to the correct voltage levels (as described in [Table](#page-12-0) 1 to Table 3). There is no need to apply <sup>a</sup> reset pulse.

Frequently used functions are controlled in this mode — standby, selection between LVDS/CMOS output format, internal/external reference, and 2s complement/straight binary output format.



#### **Figure 4. Simple Scheme to Configure Parallel Pins**

#### *DESCRIPTION OF PARALLEL PINS*

#### **Table 1. SCLK (Analog Control Pin)**



#### **Table 2. SEN (Analog Control Pin)**



<span id="page-12-0"></span>

## **Table 3. SDATA, PDN (Digital Control Pins)**

## **SERIAL INTERFACE**

The ADC has <sup>a</sup> set of internal registers, which can be accessed through the serial interface formed by pins SEN (Serial interface Enable), SCLK (Serial Interface Clock), SDATA (Serial Interface Data) and RESET. After device power-up, the internal registers must be reset to their default values by applying <sup>a</sup> high-going pulse on RESET (of width greater than 10 ns).

Serial shift of bits into the device is enabled when SEN is low. Serial data SDATA is latched at every falling edge of SCLK when SEN is active (low). The serial data is loaded into the register at every 16th SCLK falling edge when SEN is low. If the word length exceeds <sup>a</sup> multiple of 16 bits, the excess bits are ignored. Data is loaded in multiples of 16-bit words within <sup>a</sup> single active SEN pulse.

The first 5 bits form the register address and the remaining 11 bits form the register data.

The interface can work with <sup>a</sup> SCLK frequency from 20 MHz down to very low speeds (a few hertz) and also with <sup>a</sup> non-50% SCLK duty cycle.



#### **Figure 5. Serial Interface Timing Diagram**

#### **REGISTER INITIALIZATION**

After power-up, the internal registers *must* be reset to their default values. This is done in one of two ways:

1. Either through <sup>a</sup> hardware reset by applying <sup>a</sup> high-going pulse on the RESET pin (width greater than 10 ns) as shown in Figure 5.

OR

2. By applying <sup>a</sup> software reset. Using the serial interface, set the <RST> bit (D4 in register 0x00) to *high*. This initializes the internal registers to their default values and then self-resets the <RST> bit to *low*. In this case the RESET pin is kept *low*.

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## **SERIAL INTERFACE TIMING**

Typical values at 25°C, min and max values across the full temperature range  $T_{MIN} = -40^{\circ}C$  to  $T_{MAX} = 85^{\circ}C$ , AVDD <sup>=</sup> DRVDD <sup>=</sup> 3.3 V (unless otherwise noted)



## **RESET TIMING**

Typical values at 25°C, min and max values across the full temperature range  $T_{MIN} = -40^{\circ}C$  to  $T_{MAX} = 85^{\circ}C$ , AVDD <sup>=</sup> DRVDD <sup>=</sup> 3.3 V (unless otherwise noted)





NOTE: A high-going pulse on the RESET pin is required in serial interface mode in the case of initialization through <sup>a</sup> hardware reset. For parallel interface operation, RESET has to be tied permanently HIGH.

**Figure 6. Reset Timing Diagram**



## **SERIAL REGISTER MAP**

Table 4 gives <sup>a</sup> summary of all the modes that can be programmed through the serial interface.



## **Table 4. Summary of Functions Supported by Serial Interface(1)(2)**

(1) The unused bits in each register (shown by blank cells in above table) must be programmed as '0'.

(2) Multiple functions in <sup>a</sup> register can be programmed in <sup>a</sup> single write operation.

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## **DESCRIPTION OF SERIAL REGISTERS**

Each register function is explained in detail.





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#### **Table 6.**

<span id="page-16-0"></span>



- 0 Default output clock position after reset. The setup/hold timings for this clock position are specified in the timing specifications table.
- 1 Output clock shifted (delayed) by 400 ps

#### **D9 <CLKOUT EDGE>**

- 0 Use rising edge to capture data
- 1 Use falling edge to capture data

#### **D10 <DATAOUT\_POSN>**

- 0 Default position (after reset)
- 1 Data transition delayed by half clock cycle with respect to default position

#### **Table 7.**



#### **D10 Bit-wise or byte-wise selection (DDR LVDS mode only)**

- 0 Bit-wise sequence Even data bits (D0, D2, D4,..D12) are output at the rising edge of CLKOUTP and odd data bits (D1, D3, D5,..D13) at the falling edge of CLKOUTP
- 1 Byte-wise sequence Lower 7 data bits (D0-D7) are output at the rising edge of CLKOUTP and upper 7 data bits (D8-D13) at the falling edge of CLKOUTP

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**Table 8.**



## **D7-D5 Test patterns**



001 All zeros - <D13:D0> <sup>=</sup> 0x0000

010 All ones - <D13:D0> <sup>=</sup> 0x3FFF

- 011 Toggle pattern <D13:D0> toggles between 0x2AAA and 0x1555
- 100 Digital ramp <D13:D0> increments from 0x0000 to 0x3FFF by one code every cycle
- 101 Custom pattern <D13:D0> <sup>=</sup> contents of CUSTOM PATTERN registers
- 110 Unused
- 111 Unused

#### **D10 <DATA FORMAT>**

- 0 2s Complement
- 1 Straight binary

#### **Table 9.**



#### **Table 10.**







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## **Table 11.**





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## **Table 12.**





combinations

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#### **PIN CONFIGURATION (CMOS MODE)**



**Figure 7. CMOS Mode Pinout**

#### **PIN ASSIGNMENTS – CMOS Mode**



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#### **PIN CONFIGURATION (LVDS MODE)**

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**Figure 8. LVDS Mode Pinout**

#### **PIN ASSIGNMENTS – LVDS Mode**



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#### **PIN ASSIGNMENTS – LVDS Mode (continued)**



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#### **TYPICAL CHARACTERISTICS - ADS6145 (FS<sup>=</sup> 125 MSPS)**

All plots are at 25°C, AVDD = DRVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock, 1.5 V<sub>PP</sub> differential clock amplitude, 50% clock duty cycle, –1 dBFS differential analog input, internal reference mode, 0 dB gain, CMOS output interface (unless otherwise noted)



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**TYPICAL CHARACTERISTICS - ADS6145 (FS<sup>=</sup> 125 MSPS) (continued)**

All plots are at 25°C, AVDD = DRVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock, 1.5 V<sub>PP</sub> differential clock amplitude, 50% clock duty cycle, –1 dBFS differential analog input, internal reference mode, 0 dB gain, CMOS output interface (unless otherwise noted)



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**TYPICAL CHARACTERISTICS - ADS6145 (FS<sup>=</sup> 125 MSPS) (continued)**

All plots are at 25°C, AVDD = DRVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock, 1.5 V<sub>PP</sub> differential clock amplitude, 50% clock duty cycle, –1 dBFS differential analog input, internal reference mode, 0 dB gain, CMOS output interface (unless otherwise noted)







## **TYPICAL CHARACTERISTICS - ADS6144 (FS<sup>=</sup> 105 MSPS)**

All plots are at 25°C, AVDD = DRVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock, 1.5 V<sub>PP</sub> differential clock amplitude, 50% clock duty cycle, –1 dBFS differential analog input, internal reference mode, 0 dB gain, CMOS output interface (unless otherwise noted)



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## **TYPICAL CHARACTERISTICS - ADS6144 (FS<sup>=</sup> 105 MSPS) (continued)**

All plots are at 25°C, AVDD = DRVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock, 1.5 V<sub>PP</sub> differential clock amplitude, 50% clock duty cycle, –1 dBFS differential analog input, internal reference mode, 0 dB gain, CMOS output interface (unless otherwise noted)



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**TYPICAL CHARACTERISTICS - ADS6144 (FS<sup>=</sup> 105 MSPS) (continued)**

All plots are at 25°C, AVDD = DRVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock, 1.5 V<sub>PP</sub> differential clock amplitude, 50% clock duty cycle, –1 dBFS differential analog input, internal reference mode, 0 dB gain, CMOS output interface (unless otherwise noted)



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# clock amplitude, 50% clock duty cycle, –1 dBFS differential analog input, internal reference mode, 0 dB gain, CMOS output

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**TYPICAL CHARACTERISTICS - ADS6143 (FS<sup>=</sup> 80 MSPS)**

All plots are at 25°C, AVDD = DRVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock, 1.5 V<sub>PP</sub> differential

interface (unless otherwise noted)

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**TYPICAL CHARACTERISTICS - ADS6143 (FS<sup>=</sup> 80 MSPS) (continued)**

All plots are at 25°C, AVDD = DRVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock, 1.5 V<sub>PP</sub> differential clock amplitude, 50% clock duty cycle, –1 dBFS differential analog input, internal reference mode, 0 dB gain, CMOS output interface (unless otherwise noted)



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## **TYPICAL CHARACTERISTICS - ADS6143 (FS<sup>=</sup> 80 MSPS) (continued)**

All plots are at 25°C, AVDD = DRVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock, 1.5 V<sub>PP</sub> differential clock amplitude, 50% clock duty cycle, –1 dBFS differential analog input, internal reference mode, 0 dB gain, CMOS output interface (unless otherwise noted)



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## **TYPICAL CHARACTERISTICS - ADS6142 (FS<sup>=</sup> 65 MSPS)**

All plots are at 25°C, AVDD = DRVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock, 1.5  $V_{PP}$  differential clock amplitude, 50% clock duty cycle, –1 dBFS differential analog input, internal reference mode, 0 dB gain, CMOS output interface (unless otherwise noted)



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## **TYPICAL CHARACTERISTICS - ADS6142 (FS<sup>=</sup> 65 MSPS) (continued)**

All plots are at 25°C, AVDD = DRVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock, 1.5 V<sub>PP</sub> differential clock amplitude, 50% clock duty cycle, –1 dBFS differential analog input, internal reference mode, 0 dB gain, CMOS output interface (unless otherwise noted)







## **TYPICAL CHARACTERISTICS - ADS6142 (FS<sup>=</sup> 65 MSPS) (continued)**

All plots are at 25°C, AVDD = DRVDD = 3.3 V, maximum rated sampling frequency, sine wave input clock, 1.5 V<sub>PP</sub> differential clock amplitude, 50% clock duty cycle, –1 dBFS differential analog input, internal reference mode, 0 dB gain, CMOS output interface (unless otherwise noted)



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**TYPICAL CHARACTERISTICS - LOW SAMPLING FREQUENCIES**

All plots are at 25°C, AVDD = DRVDD = 3.3 V, sine wave input clock, 1.5 V<sub>PP</sub> differential clock amplitude, 50% clock duty cycle, –1 dBFS differential analog input, internal reference mode, 0 dB gain, CMOS output interface (unless otherwise noted)



 $F_s = 40$  MSPS





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#### **COMMON PLOTS**

All plots are at 25°C, AVDD = DRVDD = 3.3 V, sine wave input clock, 1.5 V<sub>PP</sub> differential clock amplitude, 50% clock duty cycle, –1 dBFS differential analog input, internal reference mode, 0 dB gain, CMOS output interface (unless otherwise noted)



**DRVDD current vs SAMPLING FREQUENCY ACROSS LOAD CAPACITANCE (CMOS)**





**Contour Plots Across Input and Sampling Frequencies**





**Figure** 89. **SFDR** Contour (with 3.5 dB coarse gain,  $F_s = 1.34 V_{PP}$ )



**Figure** 90. **SNR** Contour (no gain,  $F_s = 2 V_{PP}$ )



**Figure** 91. **SNR Contour** (with 3.5 dB coarse gain,  $F_s = 1.34 V_{PP}$ )

## **APPLICATION INFORMATION**

## **THEORY OF OPERATION**

The ADS614X devices are <sup>a</sup> family of low power, 14-bit pipeline ADCs in <sup>a</sup> CMOS process with up to <sup>a</sup> 125 MSPS sampling frequencies. These devices are based on switched capacitor technology and run off <sup>a</sup> single 3.3-V supply. The conversion process is initiated by the rising edge of the external input clock. Once the signal is captured by the input sample and hold, the input sample is sequentially converted by <sup>a</sup> series of lower resolution stages, with the outputs combined in <sup>a</sup> digital correction logic block. At every clock edge, the sample propagates through the pipeline resulting in <sup>a</sup> data latency of 9 clock cycles. The output is available as 14-bit data, in DDR LVDS or CMOS and coded in either straight offset binary or binary 2s complement format.

## **ANALOG INPUT**

The analog input consists of <sup>a</sup> switched-capacitor based differential sample and hold architecture, shown in Figure 92.

This differential topology results in good ac-performance even for high input frequencies at high sampling rates. The INP and INM pins have to be externally biased around a common-mode voltage of 1.5  $\bar{V}$  available on the VCM pin. For <sup>a</sup> full-scale differential input, each input pin (INP, INM) has to swing symmetrically between VCM <sup>+</sup> 0.5 V and VCM – 0.5 V, resulting in a 2V<sub>PP</sub> differential input swing. The maximum swing is determined by the internal reference voltages REFP (2.5 V nominal) and REFM (0.5 V, nominal).



**Figure 92. Input Stage**

The input sampling circuit has <sup>a</sup> high 3dB bandwidth that extends up to 450 MHz (measured from the input pins to the voltage across the sampling capacitors).

<span id="page-41-0"></span>

**Figure 93. ADC Analog Input Bandwidth**

#### **Drive Circuit Requirements**

For optimum performance, the analog inputs must be driven differentially. This improves the common-mode noise immunity and even-order harmonic rejection.

A 5-Ω resistor in series with each input pin is recommended to damp out ringing caused by the package parasitics. It is also necessary to present low impedance (< 50 Ω) for the common-mode switching currents. For example, this is achieved by using two resistors from each input terminated to the common-mode voltage (VCM).

In addition to the above, the drive circuit may have to be designed to provide <sup>a</sup> low insertion loss over the desired frequency range and matched impedance to the source. While doing this, the ADC input impedance (Zin) must be considered. Over <sup>a</sup> wide frequency range, the input impedance can be approximated by <sup>a</sup> parallel combination of Rin and Cin  $(Zin = Rin||Cin)$ .



**Figure 94. ADC Input Resistance, Rin**

<span id="page-42-0"></span>

**Figure 95. ADC Input Capacitance, Cin**

#### **Using RF-Transformer Based Drive Circuits**

Figure 96 shows <sup>a</sup> configuration using <sup>a</sup> single 1:1 turn ratio transformer (for example, Coilcraft WBC1-1) that can be used for low input frequencies (about 100 MHz).

The single-ended signal is fed to the primary winding of the RF transformer. The transformer is terminated on the secondary side. Putting the termination on the secondary side helps to shield the kickbacks caused by the sampling circuit from the RF transformer's leakage inductances. The termination is accomplished by two resistors connected in series, with the center point connected to the 1.5 V common mode (VCM pin). The value of the termination resistors (connected to common mode) has to be low (< 100 Ω) to provide <sup>a</sup> low-impedance path for the ADC common-mode switching current.



**Figure 96. Single Transformer Drive Circuit**

At high input frequencies, the mismatch in the transformer parasitic capacitance (between the windings) results in degraded even-order harmonic performance. Connecting two identical RF transformers back-to-back helps minimize this mismatch, and good performance is obtained for high frequency input signals. [Figure](#page-43-0) 97 shows an example using two transformers (Coilcraft WBC1-1). An additional termination resistor pair (enclosed within the dotted box in [Figure](#page-43-0) 97) may be required between the two transformers to improve the balance between the P and M sides. The center point of this termination must be connected to ground.

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<span id="page-43-0"></span>

**Figure 97. Two Transformer Drive Circuit**

#### **Using Differential Amplifier Drive Circuits**

Figure 98 shows <sup>a</sup> drive circuit using <sup>a</sup> differential amplifier (TI's THS4509) to convert <sup>a</sup> single-ended input to <sup>a</sup> differential output that can be interfaced to the ADC analog input pins. In addition to the single-ended to differential conversion, the amplifier also provides gain (10 dB in Figure 98).  $R_{FIL}$  helps to isolate the amplifier outputs from the switching input of the ADC. Together with  $C_{F|L}$  it also forms a low-pass filter that band-limits the noise (and signal) at the ADC input. As the amplifier output is ac-coupled, the common-mode voltage of the ADC input pins is set using two 200-Ω resistors connected to VCM.

The amplifier output can also be dc-coupled. Using the output common-mode control of the THS4509, the ADC input pins can be biased to 1.5 V. In this case, use +4-V and –1-V supplies for the THS4509 so that its output common-mode voltage (1.5 V) is at mid-supply.



#### **Figure 98. Drive Circuit Using the THS4509**

See the EVM User Guide [\(SLWU028](http://www-s.ti.com/sc/techlit/SLWU028)) for more information.

<span id="page-44-0"></span>

#### **Input Common Mode**

To ensure <sup>a</sup> low-noise common-mode reference, the VCM pin is filtered with <sup>a</sup> 0.1-µF low-inductance capacitor connected to ground. The VCM pin is designed to directly drive the ADC inputs. The input stage of the ADC sinks a common-mode current in the order of 180  $\mu$ A (at 125 MSPS). Equation 1 describes the dependency of the common-mode current and the sampling frequency.

$$
180 \mu A \times \frac{Fs}{125 \text{ MSPS}}
$$

(1)

Equation 1 helps to design the output capability and impedance of the CM driving circuit.

#### **REFERENCE**

The ADS614X have built-in internal references REFP and REFM, requiring no external components. Design schemes are used to linearize the converter load seen by the references; this and the integration of the requisite reference capacitors on-chip eliminates the need for external decoupling. The full-scale input range of the converter is controlled in the external reference mode as explained below. The internal or external reference modes can be selected by programming the serial interface register bit **<REF>** ([Table](#page-15-0) 5).



**Figure 99. Reference Section**

#### **Internal Reference**

When the device is in internal reference mode, the REFP and REFM voltages are generated internally. Common-mode voltage (1.5 V nominal) is output on the VCM pin, which can be used to externally bias the analog input pins.

#### **External Reference**

When the device is in external reference mode, VCM acts as <sup>a</sup> reference input pin. The voltage forced on the VCM pin is buffered and gained by 1.33 internally, generating the REFP and REFM voltages. The differential input voltage corresponding to full-scale is given by Equation 2.

Full–scale differential input pp = (Voltage forced on VCM)  $\times$  1.33

(2)

In this mode, the 1.5-V common-mode voltage to bias the input pins has to be generated externally. There is no change in performance compared to internal reference mode.

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## **COARSE GAIN AND PROGRAMMABLE FINE GAIN**

The ADS614X include gain settings that can be used to improve SFDR performance (compared to 0 dB gain mode). The gain settings are 3.5 dB coarse gain and 0 dB to 6 dB programmable fine gain. For each gain setting, the analog input full-scale range scales proportionally, as shown in Table 13.

The coarse gain is <sup>a</sup> fixed setting of 3.5 dB and is designed to improve SFDR with little degradation in SNR (as shown in [Figure](#page-24-0) 13 and Figure 14). The fine gain is programmable in 1 dB steps from 0 dB to 6 dB. With fine gain, SFDR improvement is also achieved, but at the expense of SNR (there is about 1 dB SNR degradation for every 1 dB of fine gain).

So, the fine gain can be used to trade-off between SFDR and SNR. The coarse gain makes it possible to get the best SFDR but without losing SNR significantly. At high input frequencies, the gains are especially useful as the SFDR improvement is significant with marginal degradation in SINAD. The gains can be programmed using the register bits **<COARSE GAIN>** (see [Table](#page-15-0) 5) and **<FINE GAIN>** (see [Table](#page-17-0) 10). Note that the default gain after reset is 0 dB.

GAIN, dB	<b>TYPE</b>	<b>FULL-SCALE RANGE, V<sub>PP</sub></b>
0	Default after reset	2.00
3.5	Coarse setting (fixed)	1.34
	Fine gain (programmable)	1.78
2		1.59
3		1.42
4		1.26
5		1.12
6		1.00

**Table 13. Full-Scale Range Across Gains**



## **CLOCK INPUT**

The clock inputs of the ADS614X can be driven differentially (SINE, LVPECL, or LVDS) or single-ended (LVCMOS), with little or no difference in performance between configurations. The common-mode voltage of the clock inputs is set to VCM using internal 5-k $\Omega$  resistors as shown in Figure 100. This allows the use of transformer-coupled drive circuits for the sine wave clock, or ac-coupling for the LVPECL, LVDS clock sources (see [Figure](#page-47-0) 102 and [Figure](#page-47-0) 103).

For best performance, it is recommended to drive the clock inputs differentially, reducing susceptibility to common-mode noise. In this case, it is best to connect both clock inputs to the differential input clock signal with 0.1-µF capacitors, as shown in [Figure](#page-47-0) 102. A single-ended CMOS clock can be ac-coupled to the CLKP input, with CLKM connected to ground with a 0.1-µF capacitor, as shown in [Figure](#page-47-0) 103.

For high input frequency sampling, <sup>a</sup> clock source with very low jitter is recommended. Band-pass filtering of the clock source can help reduce the effect of jitter. There is no change in performance with <sup>a</sup> non-50% duty cycle clock input. [Figure](#page-26-0) 24 shows the performance of the ADC versus clock duty cycle.



**Figure 100. Internal Clock Buffer**

<span id="page-47-0"></span>

**Figure 101. Clock Buffer Input Impedance**









<span id="page-48-0"></span>

## **POWER-DOWN MODES**

The ADS614X have four power-down modes – global power down, standby, output buffer disable, and input clock stopped. These modes can be set using the serial interface or using the parallel interface (pins SDATA and PDN).



#### **Table 14. Power-Down Modes**

#### **Global Power Down**

In this mode, the A/D converter, internal references, and the output buffers are powered down and the total power dissipation reduces to about 30 mW. The output buffers are in <sup>a</sup> high-impedance state. The wake-up time from the global power down to output data becoming valid in normal mode is <sup>a</sup> maximum of 50 µs. Note that after coming out of global power down, optimum performance is achieved after the internal reference voltages have stabilized (about 1 ms).

#### **Standby**

Only the A/D converter is powered down and total power dissipation is approximately 72 mW. The wake-up time from standby to output data becoming valid is <sup>a</sup> maximum of 50 µs.

#### **Output Buffer Disable**

The data output buffers can be disabled, reducing total power to about 408 mW. With the buffers disabled, the outputs are in <sup>a</sup> high-impedance state. The wake-up time from this mode to data becoming valid in normal mode is a maximum of 500 ns in LVDS mode and 200 ns in CMOS mode.

#### **Input Clock Stop**

The converter enters this mode when the input clock frequency falls below 1 MSPS. Power dissipation is approximately 120 mW, and the wake-up time from this mode to data becoming valid in normal mode is <sup>a</sup> maximum of 50  $\mu$ s.

#### **Power Supply Sequence**

During power-up, the AVDD and DRVDD supplies can come up in any sequence. The two supplies are separated inside the device. Externally, they can be driven from separate supplies or from <sup>a</sup> single supply.

## <span id="page-49-0"></span>**DIGITAL OUTPUT INTERFACE**

The ADS614X output 14 data bits together with an output clock. The output interface is either parallel CMOS or DDR LVDS voltage levels and can be selected using the serial register bit **<LVDS CMOS>** or parallel pin SEN.

#### **Parallel CMOS Interface**

In CMOS mode, the output buffer supply (DRVDD) can be operated over a wide range from 1.8 V to 3.3 V (typical). Each data bit is output on <sup>a</sup> separate pin as <sup>a</sup> CMOS voltage level, every clock cycle.

For DRVDD <sup>≥</sup> 2.2 V, it is recommended to use the CMOS output clock (CLKOUT) to latch data in the receiving chip. The rising edge of CLKOUT can be used to latch data in the receiver, even at the highest sampling speed (125 MSPS). It is recommended to minimize the load capacitance seen by the data and clock output pins by using short traces to the receiver. Also, match the output data and clock traces to minimize the skew between them.

For DRVDD <sup>&</sup>lt; 2.2 V, it is recommended to use an external clock (for example, input clock delayed to get desired setup/hold times).

#### *Output Clock Position Programmability*

There is an option to shift (delay) the output clock position so that the setup time increases by 400 ps (typical, with respect to the default timings specified). This may be useful if the receiver needs more setup time, especially at high sampling frequencies. This can be programmed using the serial interface register bit **<CLKOUT\_POSN>** ([Table](#page-16-0) 6).

#### *Output Buffer Strength Programmability*

Switching noise (caused by CMOS output data transitions) can couple into the analog inputs during the instant of sampling and degrade the SNR. The coupling and SNR degradation increases as the output buffer drive is made stronger. To minimize this, the ADS614X CMOS output buffers are designed with <sup>a</sup> controlled drive strength for the best SNR. The default drive strength also ensures <sup>a</sup> wide data stable window for load capacitances up to 5  $pF$  and a DRVDD supply voltage  $\geq 2.2$  V.

To ensure <sup>a</sup> wide data stable window for load capacitances <sup>&</sup>gt; 5 pF, there is an option to increase the drive strength using the serial interface (**<DRIVE STRENGTH>**, see [Table](#page-19-0) 12). Note that for <sup>a</sup> DRVDD supply voltage < 2.2 V, it is recommended to use the maximum drive strength (for any value of load capacitance).

#### *CMOS Mode Power Dissipation*

With CMOS outputs, the DRVDD current scales with the sampling frequency and the load capacitance on every output pin. The maximum DRVDD current occurs when each output bit toggles between 0 and 1 every clock cycle. In actual applications, this condition is unlikely to occur. The actual DRVDD current would be determined by the average number of output bits switching, which is <sup>a</sup> function of the sampling frequency and the nature of the analog input signal.

Digital current due to CMOS output switching =  $C_L \times DRVDD \times (N \times F_{AVG})$ 

where  $C_L$  = load capacitance, N  $\times$  F<sub>AVG</sub> = average number of output bits switching

[Figure](#page-37-0) 87 shows the current with various load capacitances across sampling frequencies with <sup>a</sup> 2-MHz analog input frequency.







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#### **DDR LVDS Interface**

The LVDS interface works only with <sup>a</sup> 3.3-V DRVDD supply. In this mode, the 14 data bits and the output clock are available as LVDS (Low Voltage Differential Signal) levels. Two successive data bits are multiplexed and output on each LVDS differential pair every clock cycle (DDR - Double Data Rate, see Figure 105 ). So, there are 7 LVDS output pairs for the 14 data bits and 1 LVDS output pair for the output clock.

#### *LVDS Buffer Current Programmability*

The default LVDS buffer output current is 3.5 mA. When terminated by 100  $\Omega$ , this results in a 350-mV single-ended voltage swing (700-m $V_{PP}$  differential swing). The LVDS buffer currents can also be programmed to 2.5 mA, 4.5 mA, and 1.75 mA (register bits **<LVDS CURRENT>**, see [Table](#page-18-0) 11). In addition, there is <sup>a</sup> current double mode, where this current is doubled for the data and output clock buffers (register bits **<CURRENT DOUBLE>**, see [Table](#page-18-0) 11).



#### **Figure 105. DDR LVDS Outputs**

<span id="page-52-0"></span>Even data bits D0, D2, D4, D6, D8, D10, and D12 are output at the rising edge of CLKOUTP and the odd data bits D1, D3, D5, D7, D9, D11, and D13 are output at the falling edge of CLKOUTP. Both the rising and falling edges of CLKOUTP must be used to capture all 14 data bits (see Figure 106).



**Figure 106. DDR LVDS Interface**

#### *LVDS Buffer Internal Termination*

An internal termination option is available (using the serial interface), by which the LVDS buffers are differentially terminated inside the device. The termination resistances available are – 300 Ω, 185 Ω, and 150 Ω (nominal with ±20% variation). Any combination of these three terminations can be programmed; the effective termination is the parallel combination of the selected resistances. This results in eight effective terminations from open (no termination) to 65 Ω.

The internal termination helps to absorb any reflections coming from the receiver end, improving the signal integrity. With 100-Ω internal and 100-Ω external termination, the voltage swing at the receiver end is halved (compared to no internal termination). The voltage swing can be restored by using the LVDS current double mode. [Figure](#page-53-0) 107 and Figure 108 compare the LVDS eye diagrams without and with internal termination (100 Ω). With internal termination, the eye looks clean even with 10-pF load capacitance (from each output pin to ground). The termination is programmed using register bits **<DATA TERM>** and **<CLKOUT TERM>** (see [Table](#page-18-0) 11).



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Figure 107. LVDS Eye Diagram - No Internal Termination<br>5-pF Load Capacitance<br>Termination<br>Termination **5-pF Load Capacitance Termination Blue Trace - Output Clock (CLKOUT) 10-pF Load Capacitance**



#### **Output Data Format**

Two output data formats are supported – 2s complement and offset binary. They can be selected using the parallel control pin SEN or the serial interface register bit **<DATA FORMAT>** (see [Table](#page-17-0) 8).

#### **Output Timings**

The tables below show the timings at lower sampling frequencies.



#### **Table 15. Timing Characteristics at Lower Sampling Frequencies (1)(2)**

(1) Timing parameters are specified by design and characterization and not tested in production.

 $(2)$  Timings are specified with default output buffer drive strength and C<sub>L</sub>= 5 pF.

<span id="page-54-0"></span>

## **BOARD DESIGN CONSIDERATIONS**

#### **Grounding**

A single ground plane is sufficient to give good performance, provided the analog, digital, and clock sections of the board are cleanly partitioned. See the EVM User Guide ([SLWU028\)](http://www-s.ti.com/sc/techlit/SLWU028) for details on layout and grounding.

#### **Supply Decoupling**

As the ADS614X already include internal decoupling, minimal external decoupling can be used without loss in performance. Note that decoupling capacitors can help filter external power supply noise, so the optimum number of capacitors would depend on the actual application. The decoupling capacitors should be placed very close to the converter supply pins.

It is recommended to use separate supplies for the analog and digital supply pins to isolate digital switching noise from sensitive analog circuitry. In case only <sup>a</sup> single 3.3-V supply is available, it should be routed first to AVDD. It can then be tapped and isolated with <sup>a</sup> ferrite bead (or inductor) with decoupling capacitor, before being routed to DRVDD.

#### **Exposed Thermal Pad**

It is necessary to solder the exposed pad at the bottom of the package to <sup>a</sup> ground plane for best thermal performance. For detailed information, see application notes *QFN Layout Guidelines* ([SLOA122](http://www-s.ti.com/sc/techlit/SLOA122)) and *QFN/SON PCB Attachment* [\(SLUA271](http://www-s.ti.com/sc/techlit/SLUA271)).



## **DEFINITION OF SPECIFICATIONS**

## **Analog Bandwidth**

The analog input frequency at which the power of the fundamental is reduced by 3 dB with respect to the low frequency value.

#### **Aperture Delay**

The delay in time between the rising edge of the input sampling clock and the actual time at which the sampling occurs.

## **Aperture Uncertainty (Jitter)**

The sample-to-sample variation in aperture delay.

#### **Clock Pulse Width/Duty Cycle**

The duty cycle of <sup>a</sup> clock signal is the ratio of the time the clock signal remains at <sup>a</sup> logic high (clock pulse width) to the period of the clock signal. Duty cycle is typically expressed as <sup>a</sup> percentage. A perfect differential sine-wave clock results in <sup>a</sup> 50% duty cycle.

#### **Maximum Conversion Rate**

The maximum sampling rate at which certified operation is given. All parametric testing is performed at this sampling rate unless otherwise noted.

#### **Minimum Conversion Rate**

The minimum sampling rate at which the ADC functions.

#### **Differential Nonlinearity (DNL)**

An ideal ADC exhibits code transitions at analog input values spaced exactly 1 LSB apart. The DNL is the deviation of any single step from this ideal value, measured in units of LSBs.

#### **Integral Nonlinearity (INL)**

The INL is the deviation of the ADC's transfer function from <sup>a</sup> best fit line determined by <sup>a</sup> least squares curve fit of that transfer function, measured in units of LSBs.

#### **Gain Error**

The gain error is the deviation of the ADC's actual input full-scale range from its ideal value. The gain error is given as <sup>a</sup> percentage of the ideal input full-scale range.

#### **Offset Error**

The offset error is the difference, given in number of LSBs, between the ADC's actual average idle channel output code and the ideal average idle channel output code. This quantity is often mapped into mV.

#### **Temperature Drift**

The temperature drift coefficient (with respect to gain error and offset error) specifies the change per degree Celsius of the parameter from  $T_{MIN}$  to  $T_{MAX}$ . It is calculated by dividing the maximum deviation of the parameter across the  $T_{MIN}$  to  $T_{MAX}$  range by the difference  $T_{MAX}-T_{MIN}$ .

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## **Signal-to-Noise Ratio**

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SNR is the ratio of the power of the fundamental ( $P_S$ ) to the noise floor power ( $P_N$ ), excluding the power at dc and the first nine harmonics.

$$
SNR = 10 \text{Log}^{10} \frac{\text{P}_\text{S}}{\text{P}_\text{N}} \tag{4}
$$

SNR is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full scale) when the power of the fundamental is extrapolated to the converter's full-scale range.

#### **Signal-to-Noise and Distortion (SINAD)**

SINAD is the ratio of the power of the fundamental  $(P<sub>S</sub>)$  to the power of all the other spectral components including noise  $(P_N)$  and distortion  $(P_D)$ , but excluding dc.

$$
SINAD = 10Log^{10} \frac{P_S}{P_N + P_D}
$$
\n
$$
\tag{5}
$$

SINAD is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full scale) when the power of the fundamental is extrapolated to the converter's full-scale range.

## **Effective Number of Bits (ENOB)**

The ENOB is <sup>a</sup> measure of <sup>a</sup> converter's performance as compared to the theoretical limit based on quantization noise.

$$
ENOB = \frac{SINAD - 1.76}{6.02}
$$

#### **Total Harmonic Distortion (THD)**

THD = 10Log<sup>10</sup>  $\frac{P_S}{P}$ 

THD is the ratio of the power of the fundamental 
$$
(P_S)
$$
 to the power of the first nine harmonics  $(P_D)$ .

$$
P_N
$$
  
 
$$
P_N
$$
  
 
$$
THD is typically given in units of 
$$
dBc
$$
 (dB to carrier).
$$

## **Spurious-Free Dynamic Range (SFDR)**

The ratio of the power of the fundamental to the highest other spectral component (either spur or harmonic). SFDR is typically given in units of dBc (dB to carrier).

#### **Two-Tone Intermodulation Distortion**

IMD3 is the ratio of the power of the fundamental (at frequencies f1 and f2) to the power of the worst spectral component at either frequency 2f1–f2 or 2f2–f1. IMD3 is either given in units of dBc (dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full scale) when the power of the fundamental is extrapolated to the converter's full-scale range.

## **DC Power Supply Rejection Ratio (DC PSRR)**

The DC PSSR is the ratio of the change in offset error to <sup>a</sup> change in analog supply voltage. The DC PSRR is typically given in units of mV/V.

$$
^{\text{tho}}
$$

(7)

(6)

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## **AC Power Supply Rejection Ratio (AC PSRR)**

AC PSRR is the measure of rejection of variations in the supply voltage of the ADC. If  $\Delta V_{SUP}$  is the change in the supply voltage and  $\Delta V_{OUT}$  is the resultant change in the ADC output code (referred to the input), then

PSRR = 20Log<sup>10</sup> 
$$
\frac{\Delta V_{OUT}}{\Delta V_{SUP}}
$$
 (Expressed in dBc)

## **Common-Mode Rejection Ratio (CMRR)**

CMRR is the measure of rejection of variations in the input common-mode voltage of the ADC. If ΔVcm is the change in the input common-mode voltage and  $\Delta V_{\text{OUT}}$  is the resultant change in the ADC output code (referred to the input), then

 $\overline{\Delta V_{CM}}$  (Expressed in dBc) CMRR = 20 $\text{Log}^{10} \frac{\Delta V_{\text{OUT}}}{\Delta V}$ 

## **Voltage Overload Recovery**

The number of clock cycles taken to recover to less than 1% error for <sup>a</sup> 6-dB overload on the analog inputs. A 6-dBFS sine wave at Nyquist frequency is used as the test stimulus.



(8)

(9)

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## **REVISION HISTORY**





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#### **PACKAGING INFORMATION**



**(1)** The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

**(2)** Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.



**TBD:** The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

**Green (RoHS & no Sb/Br):** TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

**(3)** MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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# **PACKAGE MATERIALS INFORMATION**

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## **TAPE AND REEL INFORMATION**





## **QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**





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# **PACKAGE MATERIALS INFORMATION**







NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.

B. This drawing is subject to change without notice.

C. QFN (Quad Flatpack No-Lead) Package configuration.

D. The package thermal pad must be soldered to the board for thermal and mechanical performance.

E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.

F. Falls within JEDEC MO-220.



## RHB (S-PVQFN-N32)

## PLASTIC QUAD FLATPACK NO-LEAD

#### THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No-Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.



#### NOTE: A. All linear dimensions are in millimeters



# RHB (S-PVQFN-N32)

# PLASTIC QUAD FLATPACK NO-LEAD



All linear dimensions are in millimeters. NOTES:  $A$ 

- This drawing is subject to change without notice. **B.**
- Publication IPC-7351 is recommended for alternate designs. C.
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, Quad Flat-Pack Packages, Texas Instruments Literature No. SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <http://www.ti.com>.
- E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
- F. Customers should contact their board fabrication site for recommended solder mask tolerances and via tenting recommendations for vias placed in the thermal pad.



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