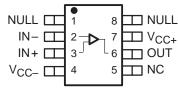
- High Speed
 - -70 MHz Bandwidth (G = 1, -3 dB)
 - 240 V/µs Slew Rate
 - 60-ns Settling Time (0.1%)
- High Output Drive, I_O = 100 mA (typ)
- Excellent Video Performance
 - 0.1 dB Bandwidth of 30 MHz (G = 1)
 - 0.01% Differential Gain
 - 0.01° Differential Phase
- Very Low Distortion
 - THD = -82 dBc (f = 1 MHz, R_I = 150 Ω)
 - THD = -89 dBc (f = 1 MHz, $R_L = 1 k\Omega$)
- Wide Range of Power Supplies
 - V_{CC} = \pm 5 V to \pm 15 V
- Available in Standard SOIC, MSOP PowerPAD™, JG or FK Package
- Evaluation Module Available

description

The THS4051 and THS4052 are general-purpose, single/dual, high-speed voltage feedback amplifiers ideal for a wide range of applications including video, communication, and imaging. The devices offer very good ac performance with 70-MHz bandwidth, 240-V/us slew rate, and 60-ns settling time (0.1%). The THS4051/2 are stable at all gains for both inverting and noninverting configurations. These amplifiers have a high output drive capability of 100 mA and draw only 8.5-mA supply current per channel. Excellent professional video results can be obtained with the low differential gain/phase errors of 0.01%/ 0.01° and wide 0.1 dB flatness to 30 MHz. For applications requiring low distortion, the THS4051/2 is ideally suited with total harmonic distortion of -82 dBc at 1 MHz.

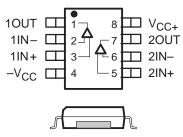
	RELATED DEVICES
DEVICE	DESCRIPTION
	290-MHz Low Distortion High-Speed Amplifiers
THS4031/2	100-MHz Low Noise High-Speed Amplifiers
THS4081/2	175-MHz Low Power High-Speed Amplifiers





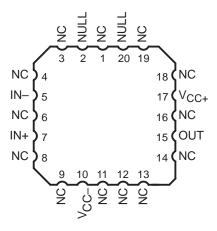
NC - No internal connection

THS4052 D AND DGN[†] PACKAGE (TOP VIEW)



Cross Section View Showing PowerPAD™ Option (DGN)

THS4051 FK PACKAGE (TOP VIEW)





CAUTION: The THS4051 and THS4052 provide ESD protection circuitry. However, permanent damage can still occur if this device is subjected to high-energy electrostatic discharges. Proper ESD precautions are recommended to avoid any performance degradation or loss of functionality.



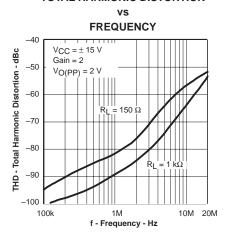
Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

PowerPAD is a trademark of Texas Instruments.



[†] This device is in the Product Preview stage of development. Please contact your local TI sales office for availability.

TOTAL HARMONIC DISTORTION



AVAILABLE OPTIONS

			PACK	AGED DEVI	CES			
TA	NUMBER OF CHANNELS	PLASTIC SMALL OUTLINE [†]	(DGN)		CERAMIC DIP	CHIP CARRIER	EVALUATION MODULE	
		(D)	DEVICE	SYMBOL	(JG)	(FK)		
0°C to 70°C	1	THS4051CD	THS4051CDGN	ACQ	_	_	THS4051EVM	
0-0 10 70-0	2	THS4052CD	THS4052CDGN [‡]	ACE	_	_	THS4052EVM	
-40°C to 85°C	1	THS4051ID	THS4051IDGN	ACR	_	_	_	
-40 C to 65 C	2	THS4052ID	THS4052IDGN [‡]	ACF	_	_	_	
-55°C to 125°C	1	_	_	_	THS4051MJG	THS4051MFK	_	

The D and DGN packages are available taped and reeled. Add an R suffix to the device type (i.e., THS4051CDGN).

functional block diagram

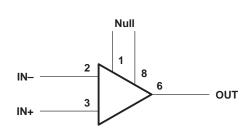


Figure 1. THS4051 - Single Channel

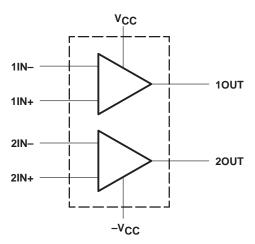


Figure 2. THS4052 - Dual Channel



[‡]This device is in the Product Preview stage of development. Please contact your local TI sales office for availability.

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absolute maximum ratings over operating free-air temperature (unless otherwise noted)†

Supply voltage, V _{CC}		±16.5 V
Input voltage, V _I		±V _{CC}
Output current, I _O		
·		
	C-suffix	
, , ,	I-suffix	–40°C to 85°C
	M-suffix	
Storage temperature, T _{sta}		–65°C to 150°C
	n) from case for 10 seconds	
Lead temperature 1,6 mm (1/16 inch	n) from case for 60 seconds, JG packag	ge 300°C
•	K package	•

[†] Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

DISSIPATION RATING TABLE

PACKAGE	θ JA (°C/W)	(°C/W)	T _A = 25°C POWER RATING
D	167‡	38.3	740 mW
DGN§	58.4	4.7	2.14 W
JG	119	28	1050 mW
FK	87.7	20	1375 mW

[†] This data was taken using the JEDEC standard Low-K test PCB. For the JEDEC Proposed High-K test PCB, the θ_{JA} is 95°C/W with a power rating at $T_A = 25$ °C of 1.32 W.

recommended operating conditions

		MIN	NOM MAX	UNIT
Supply voltage Vee, and Vee	Dual supply	±4.5	±16	V
Supply voltage, V_{CC+} and V_{CC-}	Single supply	9	32	V
	C-suffix	0	70	
Operating free-air temperature, TA	I-suffix	-40	85	°C
	M-suffix	-55	125	

[§] This data was taken using 2 oz. trace and copper pad that is soldered directly to a 3 in. ×3 in. PC. For further information, refer to *Application Information* section of this data sheet.

THS4051, THS4052 70-MHz HIGH-SPEED AMPLIFIERS

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electrical characteristics at T_A = 25°C, V_{CC} = ± 15 V, R_L = 150 Ω (unless otherwise noted)

dynamic performance

	PARAMETER	TEOT /	DONDITIONO†		THS405	xC, THS	405xI	UNIT	
	PARAMETER	TEST	CONDITIONS		MIN	TYP	MAX	UNIT	
		$V_{CC} = \pm 15 \text{ V}$		Gain = 1		70		MHz	
	Dynamic performance small-signal bandwidth (–3 dB)	$V_{CC} = \pm 5 \text{ V}$		Gairi – T		70		IVII IZ	
		V _{CC} = ±15 V		Gain = 2		38		MHz	
BW		V _{CC} = ±5 V		Gairr = 2		38		IVITIZ	
DVV	Bandwidth for 0.1 dB flatness	$V_{CC} = \pm 15 \text{ V}$		Gain = 1		30		MHz	
	Bandwidth for 0.1 dB natness	$V_{CC} = \pm 5 \text{ V}$		Gairr = 1		30			
	Full power bandwidth§	$V_{O(pp)} = 20 \text{ V}, V_{CC} = \pm 15 \text{ V}$				3.8		MHz	
	Full power bandwidths	$V_{O(pp)} = 5 \text{ V}, \text{V}$	'CC = ±5 V			12.7		IVII IZ	
SR	Class sate †	$V_{CC} = \pm 15 \text{ V}, \qquad 2$	0-V step,	Gain = 5		240		V/µs	
SK	Slew rate [‡]	$V_{CC} = \pm 5 \text{ V}, \qquad 5$	-V step	Gain = -1		200		ν/μδ	
	Cataling time to 0.40/	$V_{CC} = \pm 15 \text{ V}, 5$	-V step	Gain = -1		60		ns	
١.	Settling time to 0.1%	$V_{CC} = \pm 5 \text{ V}, \qquad 2$	-V step	Gain = -1		60			
t _S	Settling time to 0.01%	$V_{CC} = \pm 15 \text{ V}, 5$	-V step	Gain = -1		130		ns	
	Setting time to 0.01%	$V_{CC} = \pm 5 \text{ V}, \qquad 2$	-V step	Gaiii = -1		140			

[†] Full range = 0°C to 70°C for C suffix and -40°C to 85°C for I suffix

noise/distortion performance

	DADAMETED		TEST CONDITIONS†				THS405xC, THS405xI		
	PARAMETER	IES	CONDITIONS		MIN	TYP	MAX	UNIT	
			V _{CC} = ±15 V	R _L = 150 Ω		-82			
THD	Total harmonic distortion	$V_{O(pp)} = 2 \text{ V},$ f = 1 MHz, Gain = 2	VCC = ±13 V	$R_L = 1 k\Omega$		-89		dBc	
טחו	rotal narmonic distortion		V _{CC} = ±5 V	$R_L = 150 \Omega$		-78		UBC	
				R _L = 1 kΩ		-87			
٧n	Input voltage noise	$V_{CC} = \pm 5 \text{ V or } \pm 15 \text{ V},$	f = 10 kHz			14		nV/√ Hz	
In	Input current noise	$V_{CC} = \pm 5 \text{ V or } \pm 15 \text{ V},$	f = 10 kHz			0.9		pA/√Hz	
	Differential gain error	Gain = 2,	NTSC,	$V_{CC} = \pm 15 \text{ V}$		0.01%			
	Differential gain error	40 IRE modulation,	±100 IRE ramp	$V_{CC} = \pm 5 \text{ V}$		0.01%			
	Differential phase error	Gain = 2,	NTSC,	$V_{CC} = \pm 15 \text{ V}$		0.01°			
	Dillerential phase enoi	40 IRE modulation,	±100 IRE ramp	$V_{CC} = \pm 5 \text{ V}$		0.03°			
	Channel-to-channel crosstalk (THS4052 only)	$V_{CC} = \pm 5 \text{ V or } \pm 15 \text{ V},$	f = 1 MHz			– 57		dB	

[†] Full range = 0° C to 70° C for C suffix and -40° C to 85° C for I suffix.



[‡] Slew rate is measured from an output level range of 25% to 75%.

[§] Full power bandwidth = slew rate/2 π VO(Peak).

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electrical characteristics at T_A = 25°C, V_{CC} = \pm 15 V, R_L = 150 Ω (unless otherwise noted) (continued)

dc performance

	PARAMETER	7507.0	TEST CONDITIONS†			THS405xC, THS405xI		
	PARAMETER	lESI C	CONDITIONS		MIN	TYP	MAX	UNIT
		V _{CC} = ±15 V, R _L = 1 kΩ	VO = ±10 V	T _A = 25°C	5	9		V/mV
	Open loop gain	VCC = ±13 V, TC = 1 K22 VO = ±10 V	T _A = full range	3			V/IIIV	
		$V_{CC} = \pm 5 \text{ V}, R_L = 250 \Omega$ $V_O = \pm 2.5 \text{ V}$	\\o = ±2.5.\\	T _A = 25°C	2.5	6		V/mV
			V() = ±2.5 V	T _A = full range	2			V/IIIV
\/aa	Input offset voltage	V _{CC} = ±5 V or ±15 V		T _A = 25°C		2.5	10	mV
Vos	input onset voltage	ACC = 72 A OL 7.12 A		T _A = full range			12	1110
	Offset voltage drift	$V_{CC} = \pm 5 \text{ V or } \pm 15 \text{ V}$		T _A = full range		15		μV/°C
1	Input high ourrent	\\\ _+5 \\\ or \+15 \\\		T _A = 25°C		2.5	6	
IB	input bias current	Input bias current $V_{CC} = \pm 5 \text{ V or } \pm 15 \text{ V}$		T _A = full range			8	μΑ
laa	Input offset ourrent	Voc - +5 V or +15 V		T _A = 25°C		35	250	^
los	Input offset current	V _{CC} = ±5 V or ±15 V		T _A = full range	400		nA	
	Offset current drift	T _A = full range				0.3		nA/°C

[†] Full range = 0°C to 70°C for C suffix and -40°C to 85°C for I suffix

input characteristics

	PARAMETER		TEST CONDITIONS			THS405xC, THS405xI		
	PARAMETER	l I	TEST CONDITIONS†				MAX	UNIT
V. 0.5	Common-mode input voltage range	$V_{CC} = \pm 15 \text{ V}$			±13.8	±14.3		V
VICR	Common-mode input voltage range	$V_{CC} = \pm 5 \text{ V}$				±4.3		v
CMRR	Common mode rejection ratio	$V_{CC} = \pm 15 \text{ V},$	$V_{ICR} = \pm 12 V$	T _A = full range	70	100		dB
CIVIKK	Common mode rejection ratio	$V_{CC} = \pm 5 \text{ V},$	$V_{ICR} = \pm 2.5 V$		70	100		
rį	Input resistance		·			1		MΩ
Ci	Input capacitance		·	·		1.5		pF

[†] Full range = 0°C to 70°C for C suffix and -40°C to 85°C for I suffix

output characteristics

	PARAMETER	TEST CONDITIONS†		THS405xC, THS405xI			UNIT
	PARAMETER			MIN	TYP	MAX	UNIT
		$V_{CC} = \pm 15 \text{ V}$	$R_L = 250 \Omega$	±11.5	±13		V
VΟ	Output voltage swing	$V_{CC} = \pm 5 \text{ V}$	$R_L = 150 \Omega$	±3.2	±3.5		V
	Output voltage swillig	$V_{CC} = \pm 15 \text{ V}$	D 1 k0	±13	±13.6		V
		$V_{CC} = \pm 5 \text{ V}$	$R_L = 1 k\Omega$	±3.5	±3.8		
1.	Outrout surrent [†]	$V_{CC} = \pm 15 \text{ V}$	$R_1 = 20 \Omega$	80	100		mA
Io	Output current‡	$V_{CC} = \pm 5 \text{ V}$	K[= 20 12	50	75] ""A
ISC	Short-circuit current [‡]	V _{CC} = ±15 V			150	·	mA
RO	Output resistance	Open loop			13		Ω

[†] Full range = 0°C to 70°C for C suffix and -40°C to 85°C for I suffix



[‡] Observe power dissipation ratings to keep the junction temperature below the absolute maximum rating when the output is heavily loaded or shorted. See the absolute maximum ratings section of this data sheet for more information.

THS4051, THS4052 70-MHz HIGH-SPEED AMPLIFIERS

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electrical characteristics at T_A = 25°C, V_{CC} = ± 15 V, R_L = 150 Ω (unless otherwise noted) (continued) power supply

	PARAMETER	TEGT COMPLETIONS	TEST CONDITIONS†			THS405xC, THS405xI			
	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT			
Dual sup		Dual supply		±4.5		±16.5	V		
Vcc	Supply voltage operating range	Single supply				33	V		
	Construction and the second se	Voc - +15 V	T _A = 25°C		8.5	10.5			
		V _{CC} = ±15 V	T _A = full range			11.5	mA		
Icc	Supply current (per amplifier)	V 15.V	T _A = 25°C		7.5	9.5			
		$V_{CC} = \pm 5 V$	T _A = full range			10.5			
PSRR	Dower aupply rejection ratio	Voc - +5 V or +15 V	T _A = 25°C	70	84		dB		
	Power supply rejection ratio	$V_{CC} = \pm 5 \text{ V or } \pm 15 \text{ V}$	T _A = full range	68			uБ		

[†] Full range = 0°C to 70°C for C suffix and -40°C to 85°C for I suffix

electrical characteristics at T_A = full range, V_{CC} = ± 15 V, R_L = 1 k Ω (unless otherwise noted) dynamic performance

	PARAMETER		T CONDITIONS	.	TH	IS4051N	/	UNIT		
	PARAMETER	l les	ST CONDITIONS	ı	MIN	TYP	MAX	ONIT		
	Unity gain bandwidth	$V_{CC} = \pm 15 \text{ V},$	Closed loop	$R_L = 1 k\Omega$	50§	70		MHz		
		$V_{CC} = \pm 15 \text{ V}$		Gain = 1		70				
	Dynamic performance small-signal bandwidth (–3 dB)	V _{CC} = ±5 V		Gairr = 1		70		MHz		
		V _{CC} = ±15 V		Gain = 2		38		IVIITZ		
BW		V _{CC} = ±5 V		Gairr = 2		38		7		
	Bandwidth for 0.1 dB flatness	$V_{CC} = \pm 15 \text{ V}$		Gain = 1		30		MHz		
	bandwidth for 0.1 db flatness	$V_{CC} = \pm 5 \text{ V}$		Gaill = 1		30				
	Full passes has decidable	$V_{O(pp)} = 20 \text{ V},$	$V_{CC} = \pm 15 \text{ V}$		3.8			MHz		
	Full power bandwidth‡	$V_{O(pp)} = 5 V,$	$V_{CC} = \pm 5 \text{ V}$			12.7] IVIITZ		
SR	Classification	$V_{CC} = \pm 15 \text{ V},$		$R_L = 1 k\Omega$	240§	300		V/µs		
J.	Slew rate	$V_{CC} = \pm 5 \text{ V},$	5-V step	Gain = -1		200		ν/μδ		
	Settling time to 0.1%	$V_{CC} = \pm 15 \text{ V},$	5-V step	Gain = -1		60		ns		
١.	Settling time to 0.1%	$V_{CC} = \pm 5 \text{ V},$	2-V step	Gairr = -1		60				
t _S	Settling time to 0.01%	$V_{CC} = \pm 15 \text{ V},$	5-V step	Gain = −1		130		ns		
	Jetuing unie to 0.01 //	$V_{CC} = \pm 5 \text{ V},$	2-V step	Gaill = -1		140		119		

[†] Full range = -55° C to 125°C for the THS4051M.



[‡] Full power bandwidth = slew rate/2 π V_{O(Peak)}.

[§] This parameter is not tested.

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electrical characteristics at T_A = full range, V_{CC} = ± 15 V, R_L = 1 k Ω (unless otherwise noted) noise/distortion performance

	PARAMETER	TEST CONDITIONST			THS4051M			UNIT	
	TAXABLE LEX TEST CONDITIONS				MIN	TYP	MAX	UNII	
	Total harmonic distortion	$V_{O(pp)} = 2 V$, f = 1 MHz, $Gain = 2$, $T_A = 25^{\circ}C$	V _{CC} = ±15 V	$R_L = 150 \Omega$		-82			
THD				$R_L = 1 k\Omega$		-89		dBc	
11110			V _{CC} = ±5 V	$R_L = 150 \Omega$		-78		UDC	
				$R_L = 1 k\Omega$		-87			
Vn	Input voltage noise	$V_{CC} = \pm 5 \text{ V or } \pm 15 \text{ V},$ $T_A = 25^{\circ}\text{C}$	f = 10 kHz,	R _L = 150 Ω		14		nV/√ Hz	
In	Input current noise	$V_{CC} = \pm 5 \text{ V or } \pm 15 \text{ V},$ $T_A = 25^{\circ}\text{C}$	f = 10 kHz,	R _L = 150 Ω		0.9		pA/√ Hz	
	Differential and a second	Gain = 2,	NTSC,	$V_{CC} = \pm 15 \text{ V}$		0.01%			
	Differential gain error		on, ± 100 IRE ramp, $R_L = 150 \Omega$	V _{CC} = ±5 V		0.01%			
	Differential phase error	Gain = 2,	NTSC,	$V_{CC} = \pm 15 \text{ V}$	·	0.01°			
	Dilierential phase entit	40 IRE modulation, $T_A = 25^{\circ}C$,	\pm 100 IRE ramp, R _L = 150 Ω	V _{CC} = ±5 V	5 V 0.0	0.03°			

[†] Full range = –55°C to 125°C for the THS4051M.

dc performance

DADAMETED				THS4051M			
	PARAMETER	TEST CONDITIO	TEST CONDITIONS†		TYP	MAX	UNIT
		V 145 V V- 140 V	T _A = 25°C	5	9		V/mV
Ones lees sein		$V_{CC} = \pm 15 \text{ V}, \ V_{O} = \pm 10 \text{ V}$	T _A = full range	3			V/IIIV
Open loop gain	Open loop gain	V +5 V V +2 5 V	T _A = 25°C	2.5	6		V/mV
	$V_{CC} = \pm 5 \text{ V}, \ V_{O} = \pm 2.5 \text{ V}$	T _A = full range	2] v/iiiv	
VIO	Input offset voltage	V _{CC} = ±5 V or ±15 V	T _A = 25°C		2.5	10	mV
			T _A = full range			13	IIIV
	Offset voltage drift	$V_{CC} = \pm 5 \text{ V or } \pm 15 \text{ V}$	T _A = full range		15		μV/°C
1	lancet bing account	V 15V - 145V	T _A = 25°C		2.5	6	
IВ	Input bias current	$V_{CC} = \pm 5 \text{ V or } \pm 15 \text{ V}$	T _A = full range			8	μΑ
ΙΙΟ	Input offset current V _{CC}	V 15V 145V	T _A = 25°C		35	250	- A
		$V_{CC} = \pm 5 \text{ V or } \pm 15 \text{ V}$	T _A = full range			400	nA
	Offset current drift	T _A = full range			0.3		nA/°C

[†]Full range = -55°C to 125°C for the THS4051M.

input characteristics

PARAMETER		TEST CONDITIONS†			THS4051M			UNIT
					MIN	TYP	MAX	UNII
I VICE Common-mode input voltage range		V _{CC} = ±15 V			±13.8	±14.3		V
		V _{CC} = ±5 V			±3.8	±4.3		
CMRR	Common mode rejection ratio	$V_{CC} = \pm 15 \text{ V},$	$V_{ICR} = \pm 12 V$	T _A = full range	70	100		dB
CIVIKK	Common mode rejection ratio	$V_{CC} = \pm 5 \text{ V},$	V _{ICR} = ±2.5 V	TA = full range	70	100		
rį	Input resistance					1		MΩ
Ci	Input capacitance		•	•		1.5		pF

[†] Full range = -55° C to 125° C for the THS4051M.



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electrical characteristics at T_A = full range, V_{CC} = ± 15 V, R_L = 1 $k\Omega$ (unless otherwise noted) (continued)

output characteristics

PARAMETER		TEST CONDITIONS†		THS4051M			UNIT
				MIN	TYP	MAX	UNIT
		$V_{CC} = \pm 15 \text{ V}$	$R_L = 250 \Omega$	±12	±13		V
1/0	Output voltage swing	$V_{CC} = \pm 5 \text{ V}$	$R_L = 150 \Omega$	±3.2	±3.5		v
Vo	Output voltage swing	V _{CC} = ±15 V	D: 41:0	±13	±13.6		V
		$V_{CC} = \pm 5 \text{ V}$	$R_L = 1 k\Omega$	±3.2 ±3.5			
IO Output current‡		V _{CC} = ±15 V, T _A = 25°C		80	100		
	Output current [‡]	$V_{CC} = \pm 15 \text{ V},$ $T_A = \text{full range}$ $R_L = 20 \Omega$	70			mA	
		V _{CC} = ±5 V		50	75		
Isc	Short-circuit current‡	V _{CC} = ±15 V			150		mA
RO	Output resistance	Open loop			13		Ω

[†] Full range = -55° C to 125°C for the THS4051M.

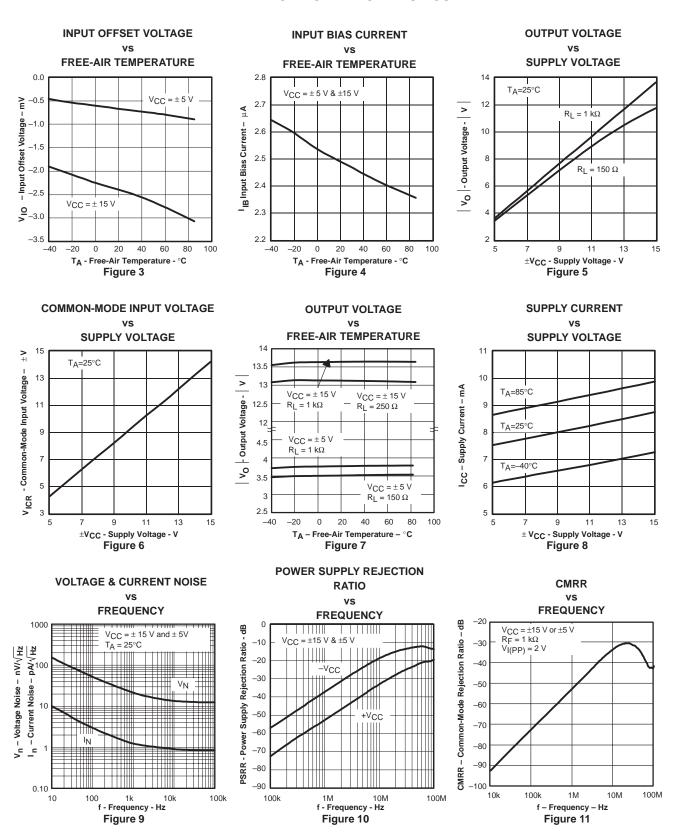
power supply

PARAMETER		TEST CONDITIONS†			THS4051M		
					TYP	MAX	UNIT
V Ourstanding of the second		Dual supply		±4.5		±16.5	V
vcc	VCC Supply voltage operating range Single supply		9		33	V	
Icc		V 145 V	T _A = 25°C		8.5	10.5	
	Cumply oursent (nor amplifier)	V _{CC} = ±15 V	T _A = full range	;		11.5	^
	Supply current (per amplifier)	V +5 V	T _A = 25°C		7.5	9.5	mA
		$V_{CC} = \pm 5 V$	T _A = full range			10.5	
PSRR	Power supply rejection ratio	V _{CC} = ±5 V or ±15 V	T _A = full range	70	84		dB

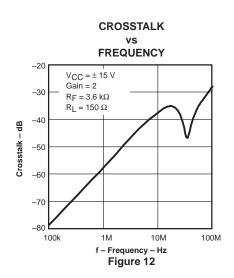
[†] Full range = -55° C to 125°C for the THS4051M.

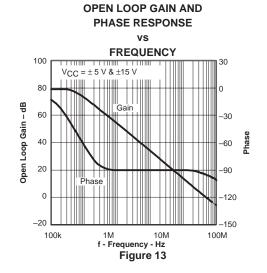


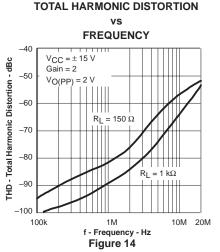
[‡] Observe power dissipation ratings to keep the junction temperature below the absolute maximum rating when the output is heavily loaded or shorted. See the absolute maximum ratings section of this data sheet for more information.

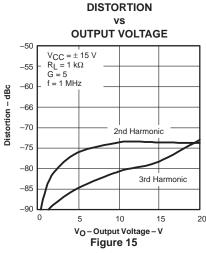


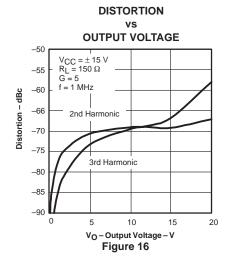


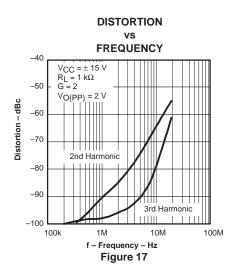


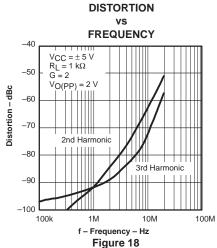


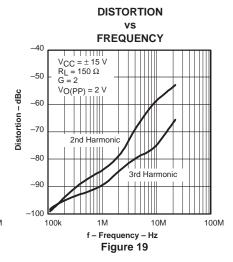


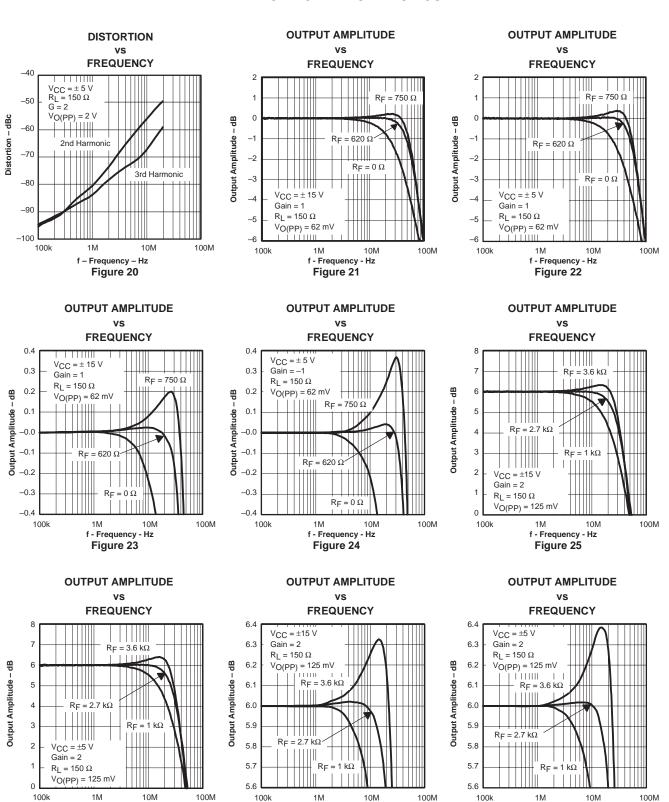














f - Frequency - Hz

Figure 27

f - Frequency - Hz

Figure 26

f - Frequency - Hz

Figure 28

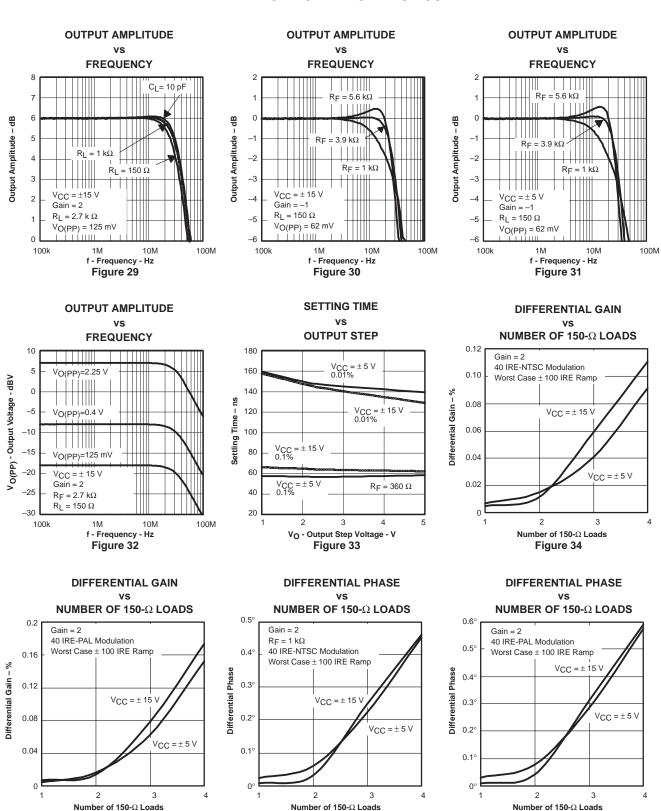
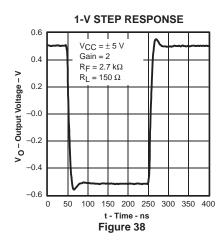


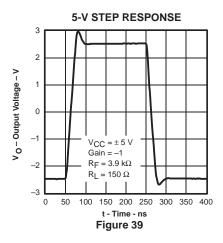


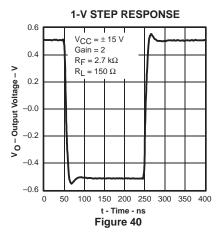
Figure 36

Figure 37

Figure 35







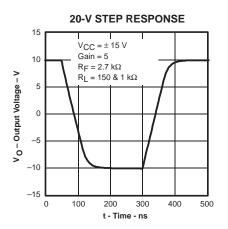


Figure 41

theory of operation

The THS405x is a high-speed, operational amplifier configured in a voltage feedback architecture. It is built using a 30-V, dielectrically isolated, complementary bipolar process with NPN and PNP transistors possessing f_{TS} of several GHz. This results in an exceptionally high performance amplifier that has a wide bandwidth, high slew rate, fast settling time, and low distortion. A simplified schematic is shown in Figure 42.

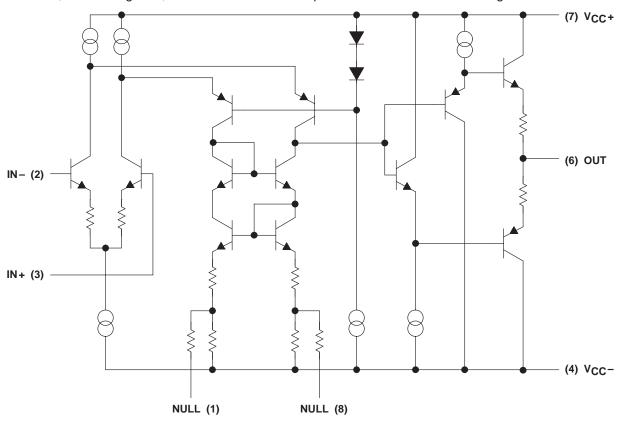


Figure 42. THS4051 Simplified Schematic

noise calculations and noise figure

Noise can cause errors on very small signals. This is especially true when amplifying small signals, where signal-to-noise ratio (SNR) is very important. The noise model for the THS405x is shown in Figure 43. This model includes all of the noise sources as follows:

- $e_n = Amplifier internal voltage noise (nV/<math>\sqrt{Hz}$)
- IN+ = Noninverting current noise (pA/ $\sqrt{\text{Hz}}$)
- IN- = Inverting current noise (pA/ $\sqrt{\text{Hz}}$)
- e_{Rx} = Thermal voltage noise associated with each resistor (e_{Rx} = 4 kTR_x)



noise calculations and noise figure (continued)

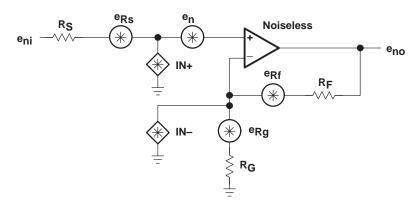


Figure 43. Noise Model

The total equivalent input noise density (eni) is calculated by using the following equation:

$$\mathbf{e}_{ni} = \sqrt{\left(\mathbf{e}_{n}\right)^{2} + \left(\mathsf{IN} + \times \mathsf{R}_{S}\right)^{2} + \left(\mathsf{IN} - \times \left(\mathsf{R}_{F} \, \| \, \mathsf{R}_{G}\right)\right)^{2} + 4 \, \mathsf{kTR}_{S} + 4 \, \mathsf{kT}\left(\mathsf{R}_{F} \, \| \, \mathsf{R}_{G}\right)}$$

Where:

 $k = Boltzmann's constant = 1.380658 \times 10^{-23}$

T = Temperature in degrees Kelvin (273 + $^{\circ}$ C)

 $R_F \parallel R_G = Parallel resistance of R_F and R_G$

To get the equivalent output noise of the amplifier, just multiply the equivalent input noise density (e_{ni}) by the overall amplifier gain (A_{V}).

$$e_{no} = e_{ni} A_V = e_{ni} \left(1 + \frac{R_F}{R_G} \right)$$
 (noninverting case)

As the previous equations show, to keep noise at a minimum, small value resistors should be used. As the closed-loop gain is increased (by reducing R_G), the input noise is reduced considerably because of the parallel resistance term. This leads to the general conclusion that the most dominant noise sources are the source resistor (R_S) and the internal amplifier noise voltage (e_n). Because noise is summed in a root-mean-squares method, noise sources smaller than 25% of the largest noise source can be effectively ignored. This can greatly simplify the formula and make noise calculations much easier to calculate.

For more information on noise analysis, please refer to the *Noise Analysis* section in *Operational Amplifier Circuits Applications Report* (literature number SLVA043).

noise calculations and noise figure (continued)

This brings up another noise measurement usually preferred in RF applications, the noise figure (NF). Noise figure is a measure of noise degradation caused by the amplifier. The value of the source resistance must be defined and is typically 50 Ω in RF applications.

$$NF = 10log \left[\frac{e_{ni}^2}{\left(e_{Rs}\right)^2} \right]$$

Because the dominant noise components are generally the source resistance and the internal amplifier noise voltage, we can approximate noise figure as:

$$NF = 10log \left[1 + \frac{\left(\left(e_n \right)^2 + \left(IN + \times R_S \right)^2 \right)}{4 \text{ kTR}_S} \right]$$

Figure 44 shows the noise figure graph for the THS405x.

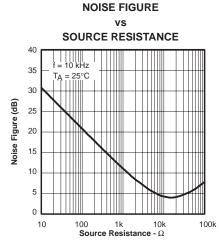


Figure 44. Noise Figure vs Source Resistance

driving a capacitive load

Driving capacitive loads with high performance amplifiers is not a problem as long as certain precautions are taken. The first is to realize that the THS405x has been internally compensated to maximize its bandwidth and slew rate performance. When the amplifier is compensated in this manner, capacitive loading directly on the output will decrease the device's phase margin leading to high frequency ringing or oscillations. Therefore, for capacitive loads of greater than 10 pF, it is recommended that a resistor be placed in series with the output of the amplifier, as shown in Figure 45. A minimum value of 20 Ω should work well for most applications. For example, in 75- Ω transmission systems, setting the series resistor value to 75 Ω both isolates any capacitance loading and provides the proper line impedance matching at the source end.

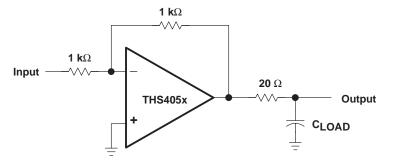


Figure 45. Driving a Capacitive Load

offset nulling

The THS405x has very low input offset voltage for a high-speed amplifier. However, if additional correction is required, an offset nulling function has been provided on the THS4051. The input offset can be adjusted by placing a potentiometer between terminals 1 and 8 of the device and tying the wiper to the negative supply. This is shown in Figure 46.

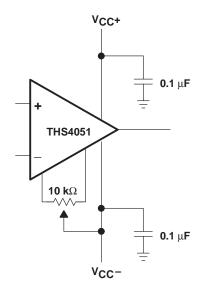
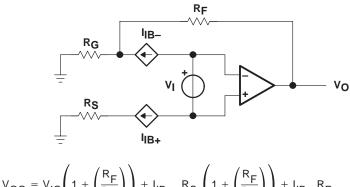


Figure 46. Offset Nulling Schematic



offset voltage

The output offset voltage, (V_{OO}) is the sum of the input offset voltage (V_{IO}) and both input bias currents (I_{IB}) times the corresponding gains. The following schematic and formula can be used to calculate the output offset voltage:



$$V_{OO} = V_{IO} \left(1 + \left(\frac{R_F}{R_G} \right) \right) \pm I_{IB+} R_S \left(1 + \left(\frac{R_F}{R_G} \right) \right) \pm I_{IB-} R_F$$

Figure 47. Output Offset Voltage Model

optimizing unity gain response

Internal frequency compensation of the THS405x was selected to provide very wideband performance yet still maintain stability when operated in a noninverting unity gain configuration. When amplifiers are compensated in this manner there is usually peaking in the closed loop response and some ringing in the step response for very fast input edges, depending upon the application. This is because a minimum phase margin is maintained for the G=+1 configuration. For optimum settling time and minimum ringing, a feedback resistor of $620\,\Omega$ should be used as shown in Figure 48. Additional capacitance can also be used in parallel with the feedback resistance if even finer optimization is required.

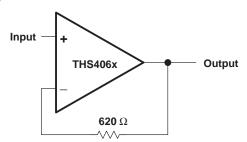


Figure 48. Noninverting, Unity Gain Schematic

general configurations

When receiving low-level signals, limiting the bandwidth of the incoming signals into the system is often required. The simplest way to accomplish this is to place an RC filter at the noninverting terminal of the amplifier (see Figure 49).

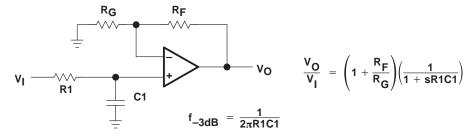


Figure 49. Single-Pole Low-Pass Filter

If even more attenuation is needed, a multiple pole filter is required. The Sallen-Key filter can be used for this task. For best results, the amplifier should have a bandwidth that is 8 to 10 times the filter frequency bandwidth. Failure to do this can result in phase shift of the amplifier.

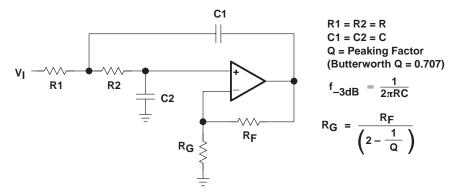


Figure 50. 2-Pole Low-Pass Sallen-Key Filter

circuit layout considerations

To achieve the levels of high frequency performance of the THS405x, follow proper printed-circuit board high frequency design techniques. A general set of guidelines is given below. In addition, a THS405x evaluation board is available to use as a guide for layout or for evaluating the device performance.

- Ground planes It is highly recommended that a ground plane be used on the board to provide all
 components with a low inductive ground connection. However, in the areas of the amplifier inputs and
 output, the ground plane can be removed to minimize the stray capacitance.
- Proper power supply decoupling Use a 6.8-μF tantalum capacitor in parallel with a 0.1-μF ceramic capacitor on each supply terminal. It may be possible to share the tantalum among several amplifiers depending on the application, but a 0.1-μF ceramic capacitor should always be used on the supply terminal of every amplifier. In addition, the 0.1-μF capacitor should be placed as close as possible to the supply terminal. As this distance increases, the inductance in the connecting trace makes the capacitor less effective. The designer should strive for distances of less than 0.1 inches between the device power terminals and the ceramic capacitors.
- Sockets Sockets are not recommended for high-speed operational amplifiers. The additional lead inductance in the socket pins will often lead to stability problems. Surface-mount packages soldered directly to the printed-circuit board is the best implementation.
- Short trace runs/compact part placements Optimum high frequency performance is achieved when stray series inductance has been minimized. To realize this, the circuit layout should be made as compact as possible, thereby minimizing the length of all trace runs. Particular attention should be paid to the inverting input of the amplifier. Its length should be kept as short as possible. This will help to minimize stray capacitance at the input of the amplifier.
- Surface-mount passive components Using surface-mount passive components is recommended for high
 frequency amplifier circuits for several reasons. First, because of the extremely low lead inductance of
 surface-mount components, the problem with stray series inductance is greatly reduced. Second, the small
 size of surface-mount components naturally leads to a more compact layout thereby minimizing both stray
 inductance and capacitance. If leaded components are used, it is recommended that the lead lengths be
 kept as short as possible.

general PowerPAD™ design considerations

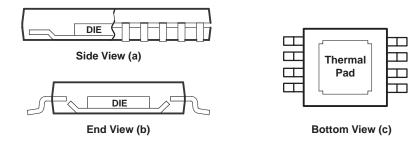
The THS405x is available packaged in a thermally-enhanced DGN package, which is a member of the PowerPAD™ family of packages. This package is constructed using a downset leadframe upon which the die is mounted [see Figure 51(a) and Figure 51(b)]. This arrangement results in the lead frame being exposed as a thermal pad on the underside of the package [see Figure 51(c)]. Because this thermal pad has direct thermal contact with the die, excellent thermal performance can be achieved by providing a good thermal path away from the thermal pad.

The PowerPADTM package allows for both assembly and thermal management in one manufacturing operation. During the surface-mount solder operation (when the leads are being soldered), the thermal pad can also be soldered to a copper area underneath the package. Through the use of thermal paths within this copper area, heat can be conducted away from the package into either a ground plane or other heat dissipating device.

The PowerPAD™ package represents a breakthrough in combining the small area and ease of assembly of the surface mount with the, heretofore, awkward mechanical methods of heatsinking.



general PowerPAD™ design considerations (continued)



NOTE A: The thermal pad is electrically isolated from all terminals in the package.

Figure 51. Views of Thermally Enhanced DGN Package

Although there are many ways to properly heatsink this device, the following steps illustrate the recommended approach.

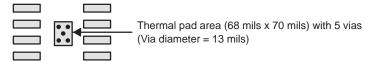


Figure 52. PowerPAD™ PCB Etch and Via Pattern

- 1. Prepare the PCB with a top side etch pattern as shown in Figure 52. There should be etch for the leads as well as etch for the thermal pad.
- 2. Place five holes in the area of the thermal pad. These holes should be 13 mils in diameter. Keep them small so that solder wicking through the holes is not a problem during reflow.
- 3. Additional vias may be placed anywhere along the thermal plane outside of the thermal pad area. This helps dissipate the heat generated by the THS405xDGN IC. These additional vias may be larger than the 13-mil diameter vias directly under the thermal pad. They can be larger because they are not in the thermal pad area to be soldered so that wicking is not a problem.
- 4. Connect all holes to the internal ground plane.
- 5. When connecting these holes to the ground plane, do not use the typical web or spoke via connection methodology. Web connections have a high thermal resistance connection that is useful for slowing the heat transfer during soldering operations. This makes the soldering of vias that have plane connections easier. In this application, however, low thermal resistance is desired for the most efficient heat transfer. Therefore, the holes under the THS405xDGN package should make their connection to the internal ground plane with a complete connection around the entire circumference of the plated-through hole.
- 6. The top-side solder mask should leave the terminals of the package and the thermal pad area with its five holes exposed. The bottom-side solder mask should cover the five holes of the thermal pad area. This prevents solder from being pulled away from the thermal pad area during the reflow process.
- 7. Apply solder paste to the exposed thermal pad area and all of the IC terminals.
- 8. With these preparatory steps in place, the THS405xDGN IC is simply placed in position and run through the solder reflow operation as any standard surface-mount component. This results in a part that is properly installed.



general PowerPAD™ design considerations (continued)

The actual thermal performance achieved with the THS405xDGN in its PowerPADTM package depends on the application. In the example above, if the size of the internal ground plane is approximately 3 inches \times 3 inches, then the expected thermal coefficient, θ_{JA} , is about 58.4°C/W. For comparison, the non-PowerPADTM version of the THS405x IC (SOIC) is shown. For a given θ_{JA} , the maximum power dissipation is shown in Figure 53 and is calculated by the following formula:

$$\mathsf{P}_\mathsf{D} = \left(\frac{\mathsf{T}_\mathsf{MAX}^{-\mathsf{T}}\mathsf{A}}{\theta_\mathsf{JA}}\right)$$

Where:

P_D = Maximum power dissipation of THS405x IC (watts)

T_{MAX} = Absolute maximum junction temperature (150°C)

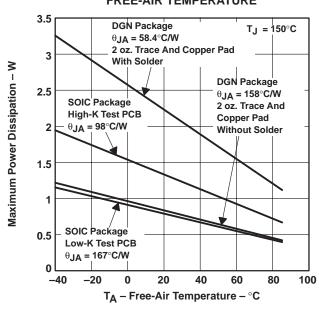
 T_A = Free-ambient air temperature (°C)

 $\theta_{JA} = \theta_{JC} + \theta_{CA}$

 θ_{JC} = Thermal coefficient from junction to case

 θ_{CA} = Thermal coefficient from case to ambient air (°C/W)

MAXIMUM POWER DISSIPATION vs FREE-AIR TEMPERATURE



NOTE A: Results are with no air flow and PCB size = $3"\times 3"$

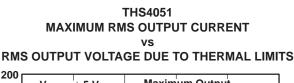
Figure 53. Maximum Power Dissipation vs Free-Air Temperature

More complete details of the PowerPAD™ installation process and thermal management techniques can be found in the Texas Instruments Technical Brief, *PowerPAD™ Thermally Enhanced Package*. This document can be found at the TI web site (www.ti.com) by searching on the key word PowerPAD™. The document can also be ordered through your local TI sales office. Refer to literature number SLMA002 when ordering.



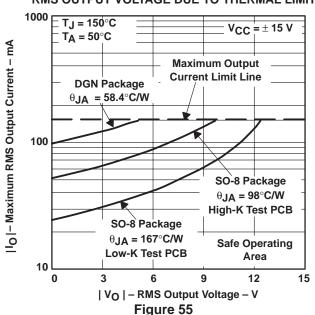
general PowerPAD™ design considerations (continued)

The next consideration is the package constraints. The two sources of heat within an amplifier are quiescent power and output power. The designer should never forget about the quiescent heat generated within the device, especially devices with multiple amplifiers. Because these devices have linear output stages (Class A-B), most of the heat dissipation is at low output voltages with high output currents. Figure 54 to Figure 57 show this effect, along with the guiescent heat, with an ambient air temperature of 50°C. Obviously, as the ambient temperature increases, the limit lines shown will drop accordingly. The area under each respective limit line is considered the safe operating area. Any condition above this line will exceed the amplifier's limits and failure may result. When using $V_{CC} = \pm 5 \text{ V}$, there is generally not a heat problem, even with SOIC packages. But, when using V_{CC} = ± 15 V, the SOIC package is severely limited in the amount of heat it can dissipate. The other key factor when looking at these graphs is how the devices are mounted on the PCB. The PowerPAD™ devices are extremely useful for heat dissipation. But, the device should always be soldered to a copper plane to fully use the heat dissipation properties of the PowerPAD™. The SOIC package, on the other hand, is highly dependent on how it is mounted on the PCB. As more trace and copper area is placed around the device, θ_{JA} decreases and the heat dissipation capability increases. The currents and voltages shown in these graphs are for the total package. For the dual amplifier package (THS4052), the sum of the RMS output currents and voltages should be used to choose the proper package. The graphs shown assume that both amplifier's outputs are identical.



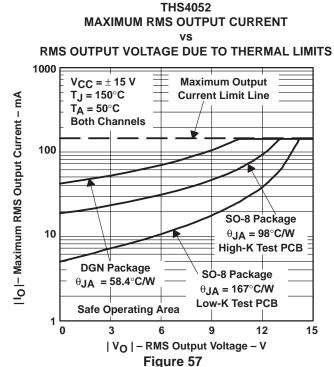
200 $V_{CC} = \pm 5 V$ **Maximum Output Current Limit Line** T_i = 150°C Io |- Maximum RMS Output Current - mA 180 $T_A = 50^{\circ}C$ 160 140 **Package With** 120 θ_{JA} < = 120°C/W 100 SO-8 Package 80 θ_{JA} = 167°C/W **Low-K Test PCB** 60 40 Safe Operating 20 Area 0 3 0 2 5 | VO | - RMS Output Voltage - V Figure 54

THS4051 MAXIMUM RMS OUTPUT CURRENT vs RMS OUTPUT VOLTAGE DUE TO THERMAL LIMITS



general PowerPAD™ design considerations (continued)

THS4052 MAXIMUM RMS OUTPUT CURRENT vs RMS OUTPUT VOLTAGE DUE TO THERMAL LIMITS **Maximum Output** Package With **Current Limit Line** $\theta_{JA} \le 60^{\circ} \text{C/W}$ | Io |- Maximum RMS Output Current - mA 180 160 140 120 100 SO-8 Package $\theta_{JA} = 167^{\circ}\text{C/W}$ 80 **Low-K Test PCB** 60 Safe Operating Area $V_{CC} = \pm 5 V$ 40 SO-8 Package T_J = 150°C $\theta_{\text{J}}\Delta = 98^{\circ}\text{C/W}$ $T_A = 50^{\circ}C$ 20 High-K Test PCB **Both Channels** 0 2 3 5 | V_O | – RMS Output Voltage – V Figure 56



evaluation board

An evaluation board is available for the THS4051 (literature number SLOP220) and THS4052 (literature number SLOP234). This board has been configured for very low parasitic capacitance in order to realize the full performance of the amplifier. A schematic of the evaluation board is shown in Figure 58. The circuitry has been designed so that the amplifier may be used in either an inverting or noninverting configuration. For more information, please refer to the *THS4051 EVM User's Guide* or the *THS4052 EVM User's Guide*. To order the evaluation board, contact your local TI sales office or distributor.

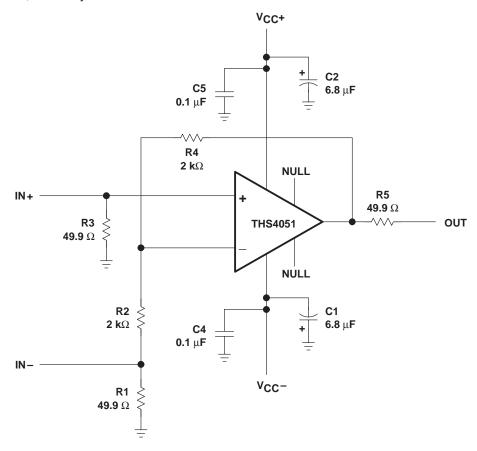


Figure 58. THS4051 Evaluation Board

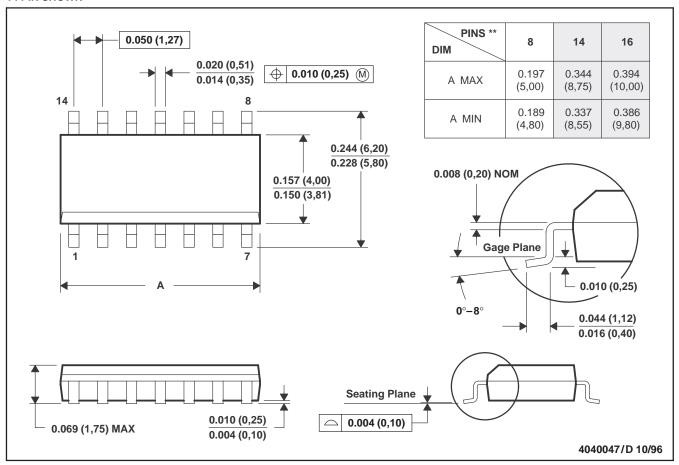
SLOS238C- MAY 1999 - REVISED MAY 2000

MECHANICAL INFORMATION

D (R-PDSO-G**)

PLASTIC SMALL-OUTLINE PACKAGE

14 PIN SHOWN



NOTES: A. All linear dimensions are in inches (millimeters).

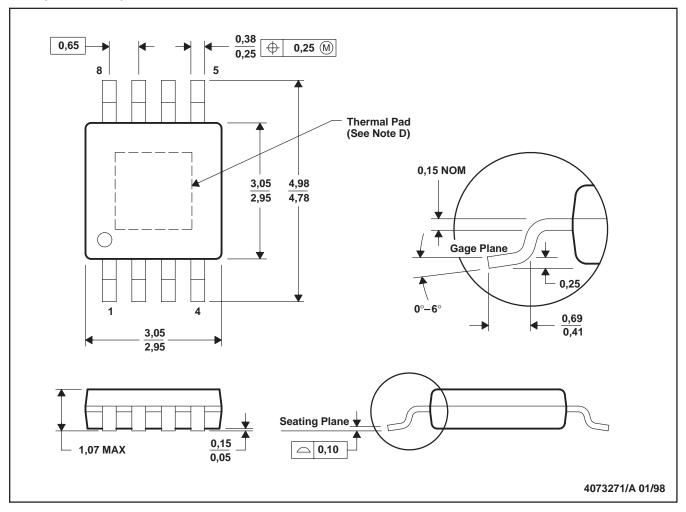
- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion, not to exceed 0.006 (0,15).
- D. Falls within JEDEC MS-012

SLOS238C-MAY 1999 - REVISED MAY 2000

MECHANICAL INFORMATION

DGN (S-PDSO-G8)

PowerPAD™ PLASTIC SMALL-OUTLINE PACKAGE



NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Body dimensions include mold flash or protrusions.
- D. The package thermal performance may be enhanced by attaching an external heat sink to the thermal pad. This pad is electrically and thermally connected to the backside of the die and possibly selected leads.
- E. Falls within JEDEC MO-187

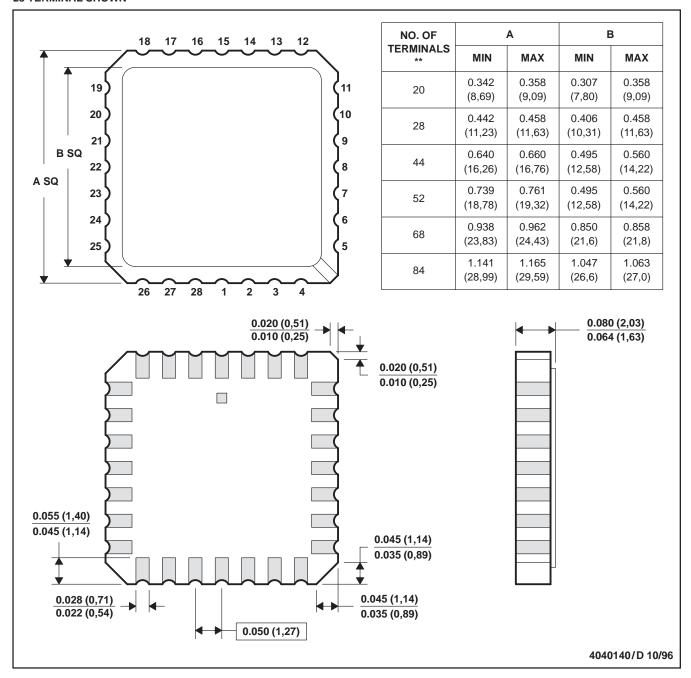
PowerPAD is a trademark of Texas Instruments.

MECHANICAL INFORMATION

FK (S-CQCC-N**)

28 TERMINAL SHOWN

LEADLESS CERAMIC CHIP CARRIER



- NOTES: A. All linear dimensions are in inches (millimeters).
 - B. This drawing is subject to change without notice.
 - C. This package can be hermetically sealed with a metal lid.
 - D. The terminals are gold plated.
 - E. Falls within JEDEC MS-004

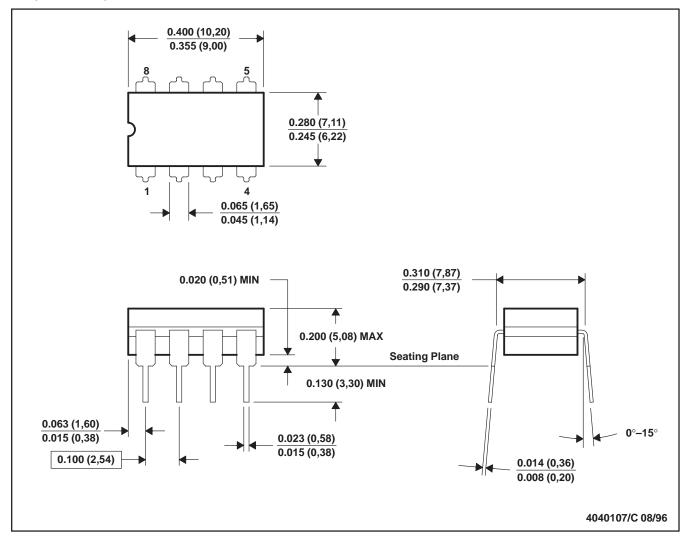


SLOS238C-MAY 1999 - REVISED MAY 2000

MECHANICAL INFORMATION

JG (R-GDIP-T8)

CERAMIC DUAL-IN-LINE PACKAGE



NOTES: A. All linear dimensions are in inches (millimeters).

- B. This drawing is subject to change without notice.
- C. This package can be hermetically sealed with a ceramic lid using glass frit.
- D. Index point is provided on cap for terminal identification only on press ceramic glass frit seal only.
- E. Falls within MIL-STD-1835 GDIP1-T8

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