- $\bullet$ **14-Bit Resolution**
- $\bullet$ **Maximum Throughput 200 KSPS**
- $\bullet$  **Analog Input Range 0-V to Reference Voltage**
- $\bullet$  **Multiple Analog Inputs:**
	- **8 Channels for TLC3548**
	- **4 Channels for TLC3544**
- $\bullet$ **Pseudodifferential Analog Inputs**
- $\bullet$  **SPI/DSP-Compatible Serial Interfaces With SCLK up to 25 MHz**
- $\bullet$  **Single 5-V Analog Supply; 3-/5-V Digital Supply**
- $\bullet$  **Low Power:**
	- **4 mA (Internal Reference: 1.8 mA) for Normal Operation – 20** µ**A in Autopower-Down**
- $\bullet$  **Built-In 4-V Reference, Conversion Clock and 8x FIFO**
- $\bullet$  **Hardware-Controlled and Programmable Sampling Period**
- $\bullet$  **Programmable Autochannel Sweep and Repeat**
- $\bullet$ **Hardware Default Configuration**
- $\bullet$ **INL:** ±**1 LSB Max**
- $\bullet$ **DNL:** ±**1 LSB Max**
- $\bullet$ **SINAD: 80.8 dB**
- $\bullet$ **THD: –95 dB**

### **description**

5 6 7 8 9 10 16 15 14 13 12 11 SDO LI  $DGND \Box$  $DV_{DD}$  $\overline{\text{cs}}$   $\Box$  $AO$   $\Box$  $A1$   $\Box$  $\Box$  REFM  $\Box$  REFP **T** AGND  $\Box$  AV<sub>DD</sub>  $\Box$  A3  $\Box$  A2 The TLC3544 and TLC3548 are a family of 14-bit resolution high-performance, low-power, CMOS analog-to-digital converters (ADC). All devices operate from a single 5-V analog power supply and 3-V to 5-V digital supply. The serial interface consists of four digital inputs [chip select (CS), frame sync (FS), serial input-output clock (SCLK), serial data input (SDI)], and a 3-state serial data output (SDO). CS (works as SS, slave select), SDI, SDO, and SCLK form an SPI interface. FS, SDI, SDO, and SCLK form a DSP interface. The frame sync signal (FS) indicates the start of a serial data frame being transferred. When multiple converters connect to one serial port of a DSP,  $\overline{CS}$  works as the chip select to allow the host DSP to access the individual converter. CS can be tied to ground if only one converter is used. FS must be tied to DV<sub>DD</sub> if it is not used (such

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as in an SPI interface). When SDI is tied to DV<sub>DD</sub>, the device is set in hardware default mode after power-on, and no software configuration is required. In the simplest case, only three wires (SDO, SCLK, and  $\overline{CS}$  or FS)

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are needed to interface with the host.



#### **DW OR PW PACKAGE (TOP VIEW)**  $10$ 24 **THE CSTART** SCLK  $\Box$ 2 23  $\Box$  AV<sub>DD</sub>  $FS \square$ 3 22 SDI O **I** AGND  $EOC/INT$   $\Box$ 4 21 **TT** BGAP 5 20  $\Box$  REFM SDO  $\square$ 6  $DGND$   $\Box$ 19 **LOO** REFP DV<sub>DD</sub> 7 18 г **TH** AGND 8 17 CS  $\Box$  AV<sub>DD</sub>  $\Box$ 9  $AO$   $\Box$ 16  $\Box$  A7 10 A1 $\Box$ 15  $\Box$  A6  $A2$   $\Box$ 11  $\Box$  A5 14  $A3 \Box$ 12 13  $\Box$  A4 **TLC3544 DW OR PW PACKAGE (TOP VIEW)** SCLK<sup>I</sup>  $10$ 20 **TH** CSTART 2 19  $FS \square$  $\Box$  AV<sub>DD</sub> SDI<sub>I</sub> 3 18 **TTT AGND** EOC/INT  $\Box$ 4 17 **TT BGAP**

**TLC3548**

### **description (continued)**

In addition to being a high-speed ADC with versatile control capability, these devices have an on-chip analog multiplexer (MUX) that can select any analog input or one of three self-test voltages. The sample-and-hold function is automatically started after the fourth SCLK (normal sampling) or can be controlled by CSTART to extend the sampling period (extended sampling). The normal sampling period can also be programmed as short sampling (12 SCLKs) or long sampling (44 SCLKs) to accommodate the faster SCLK operation popular among high-performance signal processors. The TLC3544 and TLC3548 are designed to operate with low power consumption. The power saving feature is further enhanced with software power-down/ autopower-down modes and programmable conversion speeds. The conversion clock (internal OSC) is built in. The converter can also use an external SCLK as the conversion clock for maximum flexibility. The TLC3544 and TLC3548 have a 4-V internal reference. The converters are specified with unipolar input range of 0-V to 5-V when a 5-V external reference is used.





# **functional block diagram**





# **equivalent input circuit**



**Diode Turn on Voltage: 35 V**

**Equivalent Analog Input Circuit**

**Equivalent Digital Input Circuit**





# **Terminal Functions (Continued)**





# **TLC3544, TLC3548 5-V ANALOG, 3-/5-V DIGITAL, 14-BIT, 200-KSPS, 4-/8-CHANNELS SERIAL ANALOG-TO-DIGITAL CONVERTERS WITH 0-5 V (PSEUDODIFFERENTIAL) INPUTS**

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### **absolute maximum ratings over operating free-air temperature (unless otherwise noted)†**



† Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.



**general electrical characteristics over recommended operating free-air temperature range,** single-ended input, normal long sampling, 200 KSPS, AV<sub>DD</sub> = 5 V, external reference (V<sub>REFP</sub> = 4 V, **VREFM = 0 V) or internal reference, SCLK frequency = 25 MHz, fixed channel at CONV mode 00, analog input signal source resistance = 25** Ω **(unless otherwise noted)**



 $\dagger$  All typical values are at T<sub>A</sub> = 25°C.



**general electrical characteristics over recommended operating free-air temperature range,** single-ended input, normal long sampling, 200 KSPS, AV<sub>DD</sub> = 5 V, external reference (V<sub>REFP</sub> = 4 V, **VREFM = 0 V) or internal reference, SCLK frequency = 25 MHz, fixed channel at CONV mode 00, analog input signal source resistance = 25** Ω **(unless otherwise noted) (continued)**



 $\dagger$  All typical values are at T<sub>A</sub> = 25°C.

NOTES: 1. Conversion time  $t_{(conv)} = (18x4 / SCLK) + 15$  ns.

2. This is for a fixed channel in conversion mode 00 or 01. When switching the channels, additional multiplexer setting time is required to overcome the memory effect of the charge redistribution DAC (refer to Figure 8).

3. Linear error is the maximum deviation from the best fit straight line through the A/D transfer characteristics.

4. Zero offset error is the difference between 0000000000000 and the converted output for zero input voltage; gain error is the difference between 11111111111111 and the converted output for full-scale input voltage. The full-scale input voltage is equal to the reference voltage being used.



**general electrical characteristics over recommended operating free-air temperature range,** single-ended input, normal long sampling, 200 KSPS, AV<sub>DD</sub> = 5 V, external reference (V<sub>REFP</sub> = 4V, **VREFM = 0 V) or internal reference, SCLK frequency = 25 MHz, fixed channel at CONV mode 00, analog input signal source resistance = 25** Ω **(unless otherwise noted) (continued)**



 $\dagger$  All typical values are at T<sub>A</sub> = 25°C.

NOTES: 2. This is for a fixed channel in conversion mode 00 or 01. When switching the channels, additional multiplexer setting time is required to overcome the memory effect of the charge redistribution DAC (refer to Figure 8).

3. Linear error is the maximum deviation from the best fit straight line through the A/D transfer characteristics.

4. Zero offset error is the difference between 0000000000000 and the converted output for zero input voltage; gain error is the difference between 11111111111111 and the converted output for full-scale input voltage. The full-scale input voltage is equal to the reference voltage being used.

5. It is measured by applying a full-scale of 35 kHz signal to other channels and determining how much the signal is attenuated in the channel of interest. The converter samples this examined channel continuously. The channel-to-channel isolation is degraded if the converter samples different channels alternately (refer to Figure 8).



# timing requirements over recommended operating free-air temperature range, AV<sub>DD</sub> = 5 V, DV<sub>DD</sub> **= 5 V, VREFP = 5 V, VREFM = 0 V, SCLK frequency = 25 MHz (unless otherwise noted)**

# **SCLK, SDI, SDO, EOC and INT**



† The minimum pulse width of SCLK high is 12.5 ns. The minimum pulse width of SCLK low is 12.5 ns.

‡ Specified by design

NOTE 6: For normal short sampling,  $t_{d(3)}$  is the delay from 16th falling edge of SCLK to  $\overline{\text{INT}}$  falling edge.

For normal long sampling,  $t_{d(3)}$  is the delay from 48th falling edge of SCLK to the falling edge of  $\overline{\text{INT}}$ .

Conversion time, t<sub>(CONV)</sub> is equal to 18×OSC + 15 ns when using internal OSC as conversion clock, or 72×t<sub>C(1)</sub> + 15 ns when external<br>SCLK is conversion clock source.





NOTES:  $\,$  A.  $\,$  For normal long sampling,  $\rm t_{d(2)}$  is the delay time of  $\underline{\rm EOC}$  low after the falling edge of 48th SCLK.

B. For normal long sampling,  $t_{d(3)}$  is the delay time of INT low after the falling edge of 48th SCLK. **– – – –** The dotted line means signal may or may not exist, depending on application. It must be ignored. Normal sampling mode,  $\overline{CS}$  initiates the conversion, FS must be tied to high. When  $\overline{CS}$  is high, SDO is in Hi-Z; all inputs (FS, SCLK, SDI) are inactive and are ignored.

#### **Figure 1. Critical Timing for SCLK, SDI, SDO, EOC and INT**



# **TLC3544, TLC3548 5-V ANALOG, 3-/5-V DIGITAL, 14-BIT, 200-KSPS, 4-/8-CHANNELS SERIAL ANALOG-TO-DIGITAL CONVERTERS WITH 0-5 V (PSEUDODIFFERENTIAL) INPUTS**

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### timing requirements over recommended operating free-air temperature range, AV<sub>DD</sub> = 5 V, **DVDD = 5 V, VREFP = 5 V, VREFM = 0 V, SCLK frequency = 25 MHz (unless otherwise noted) (continued)**

#### **CS trigger**



† Specified by design

 $\dagger$  For normal short sampling,  $t<sub>d</sub>(4)$  is the delay time from 16th SCLK falling edge to  $\overline{\text{CS}}$  rising edge.

For normal long sampling,  $t<sub>d</sub>(4)$  is the delay time from 48th SCLK falling edge to  $\overline{\text{CS}}$  rising edge.



NOTE A: **– – – –** The dotted line means signal may or may not exist, depending on application. It must be ignored. Normal sampling mode,  $\overline{CS}$  initiates the conversion, FS must be tied to high. When  $\overline{CS}$  is high, SDO is in Hi-Z, all inputs (FS, SCLK, SDI) are inactive and are ignored. Parts with date code earlier than 13XXXXX have these discrepancies: (Date code is a 7 digit code next to the TI where the first digit indicates the year and the second digit is the month of production. 13, in this case, is 2001 and the month of March.)

FS is not ignored even if the device is in microcontroller mode  $(\overline{CS}$  triggered). FS must be tied to DV<sub>DD</sub>.

# **Figure 2. Critical Timing for CS Trigger**



timing requirements over recommended operating free-air temperature range, AV<sub>DD</sub> = 5 V, **DVDD = 5 V, VREFP = 5 V, VREFM = 0 V, SCLK frequency = 25 MHz (unless otherwise noted) (continued)**

#### **FS trigger**



† Specified by design



NOTE A: **– – – –** The dotted line means signal may or may not exist, depending on application. It must be ignored. Normal sampling mode, FS initiates the conversion, CS can be tied to low. When CS is high, SDO is in Hi-Z, all inputs (FS, SCLK, SDI)

are inactive and are ignored.

Parts with date code earlier than 13XXXXX have these discrepancies:

(Date code is a 7 digit code next to the TI where the first digit indicates the year and the second digit is the month of production. 13, in this case, is 2001 and the month of March.)

SDO MSB (OD[15]) comes out from the falling edge of  $\overline{CS}$  instead of FS rising edge in DSP mode (FS triggered).

**Figure 3. Critical Timing for FS Trigger**



# **TLC3544, TLC3548 5-V ANALOG, 3-/5-V DIGITAL, 14-BIT, 200-KSPS, 4-/8-CHANNELS SERIAL ANALOG-TO-DIGITAL CONVERTERS WITH 0-5 V (PSEUDODIFFERENTIAL) INPUTS**

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# timing requirements over recommended operating free-air temperature range, AV<sub>DD</sub> = 5 V, DV<sub>DD</sub> = 5 V, V<sub>REFP</sub> = 5 V, V<sub>REFM</sub> = 0 V, SCLK frequency = 25 MHz (unless otherwise noted) (continued)

### **CSTART trigger**



NOTES: 7. The pulse width of CSTART must be not less than the required sampling time. The delay from CSTART rising edge to following  $\overline{\text{CSTART}}$  falling edge must not be less than the required conversion time. The delay from  $\overline{\text{CSTART}}$  rising edge to the INT falling edge is equal to the conversion time.

8. The maximum rate of SCLK is 25 MHz for normal long sampling and 10 MHz for normal short sampling.



**Extended Sampling**

**Figure 4. Critical Timing for Extended Sampling (CSTART Trigger)**

### **detailed description**

#### **converter**

The converters are a successive-approximation ADC utilizing a charge redistribution DAC. Figure 5 shows a simplified block diagram of the ADC. The sampling capacitor acquires the signal on Ain during the sampling period. When the conversion process starts, the control logic directs the charge redistribution DAC to add and subtract fixed amounts of charge from the sampling capacitor to bring the comparator into a balanced condition. When balanced, the conversion is complete and the ADC output code is generated.



### **detailed description (continued)**



#### **Figure 5. Simplified Block Diagram of the Successive-Approximation System**

#### **analog input range and internal test voltages**

TLC3548 has eight analog inputs (TLC3544 has four) and three test voltages. The inputs are selected by the analog multiplexer according to the command entered (see Table 1). The input multiplexer is a breakbefore-make type to reduce input-to-input noise injection resulting from channel switching.

The TLC3544 and TLC3548 are specified for a unipolar input range of 0-V to 4-V when the internal reference is selected, and 0-V to 5-V when an external 5-V reference is used.

#### **analog input mode**

Two input signal modes can be selected: single-ended input and pseudodifferential input.



**Figure 6. Simplified Pseudodifferential Input Circuit**

Pseudodifferential input refers to the negative input,  $Ain(-)$ ; its voltage is limited in magnitude to  $\pm 0.2$  V. The input frequency limit of Ain(–) is the same as the positive input Ain(+). This mode is normally used for ground noise rejection or dc bias offset.

When pseudodifferential mode is selected, only two analog input channel pairs are available for the TLC3544 and four channel pairs for the TLC3548, because half the inputs are used as the negative input (see Figure 7).



#### **analog input mode (continued)**



### **Figure 7. Pin Assignment of Single-Ended Input vs Pseudodifferential Input**

#### **reference voltage**

There is a built-in 4-V reference. If the internal reference is used, REFP is internally set to 4-V and REFM is set to 0-V. The external reference can be applied to the reference-input pins (REFP and REFM) if programmed (see Table 2). The REFM pin should connect to analog ground. REFP can be 3-V to 5-V. Install decoupling capacitors (10  $\mu$ F in parallel with 0.1  $\mu$ F) between REFP and REFM. Install compensation capacitors (10  $\mu$ F in parallel with 0.1 µF for internal reference, 0.1 µF only for external reference) between BGAP and AGND.



# **detailed description (continued)**

#### **ideal conversion characteristics**



**Unipolar Analog Input Voltage**

**1 LSB = 244** µ**V**

#### **data format**







# **detailed description (continued)**

#### **operation description**

The converter samples the selected analog input signal, then converts the sample into digital output, according to the selected output format. The converter has four digital input pins (SDI, SCLK,  $\overline{CS}$ , and FS) and one digital output pin (SDO) to communicate with the host device. SDI is a serial data input pin, SDO is a serial data output pin, and SCLK is a serial clock from the host device. This clock is used to clock the serial data transfer. It can also be used as the conversion clock source (see Table 2). CS and FS are used to start the operation. The converter has a CSTART pin for an external hardware sampling and conversion trigger, and an INT/EOC pin for interrupt purposes.

#### **device initialization**

After power on, the status of  $EOC/INT$  is initially high, and the input data register is set to all zeros. The device must be initialized before starting the conversion. The initialization procedure depends on the working mode. The first conversion result is ignored after power on.

**Hardware Default Mode: Nonprogrammed Mode, Default**. After power on, two consecutive active cycles initiated by  $\overline{\text{CS}}$  or FS put the device into hardware default mode if SDI is tied to DV<sub>DD</sub>. Each of these cycles must last 16 SCLKs at least. These cycles initialize the converter and load the CFR register with 800h (external reference, unipolar straight binary output code, normal long sampling, internal OSC, single-ended input, one-shot conversion mode, and  $EOC/INT$  pin as  $\overline{INT}$ . No additional software configuration is required.

**Software Programmed Mode:** Programmed. When the converter has to be configured, the host must write A000h into the converter first after power on, then perform the WRITE CFR operation to configure the device.

#### **start of operation cycle**

Each operation consists of several actions that the converter takes according to the command from the host. The operation cycle includes three periods: command period, sampling period, and conversion period. In the command period, the device decodes the command from the host. In the sampling period, the device samples the selected analog signal according to the command. In the conversion period, the sample of the analog signal is converted to digital format. The operation cycle starts from the command period, which is followed by one or several sampling and conversion periods (depending on the setting) and finishes at the end of the last conversion period.

The operation cycle is initiated by the falling edge of  $\overline{\text{CS}}$  or the rising edge of FS.

**CS Initiates The Operation:** If FS is high at the falling edge of CS, the falling edge of CS initiates the operation. When CS is high, SDO is in the high-impedance state, the signals on SDI, and SDO are ignored, and SCLK is disabled to clock the serial data. The falling edge of  $\overline{CS}$  resets the internal 4-bit counter and enables SDO, SDI, and SCLK. The MSB of the input data via SDI, ID[15], is latched at the first falling edge of SCLK following the falling edge of  $\overline{\text{CS}}$ . The MSB of output data from SDO, OD[15], is valid before this SCLK falling edge. This mode works as an SPI interface when  $\overline{\text{CS}}$  is used as the slave select ( $\overline{\text{SS}}$ ). It also can be used as a normal DSP interface if  $\overline{\text{CS}}$  connects to the frame sync output of the host DSP. FS must be tied high in this mode.

**FS Initiates The Operation:** If FS is low at the falling edge of CS, the rising edge of FS initiates the operation, resets the internal 4-bit counter, and enables SDI, SDO, and SCLK. The ID[15] is latched at the first falling edge of SCLK following the falling edge of FS. OD[15] is valid before this falling edge of SCLK. This mode is used to interface the converter with a serial port of the host DSP. The FS of the device is connected to the frame sync of the host DSP. When several devices are connected to one DSP serial port, CS is used as chip select to allow the host DSP to access each device individually. If only one converter is used,  $\overline{\text{CS}}$  can be tied low.

After the initiation, the remaining SDI data bits (if any) are shifted in and the remaining bits of SDO (if any) are shifted out at the rising edge of SCLK. The input data are latched at the falling edge of SCLK, and the output data are valid before this falling edge of SCLK. After the 4-bit counter reaches 16, the SDO goes to a high-impedance state. The output data from SDO is the previous conversion result in one shot conversion mode, or the contents in the top of the FIFO when the FIFO is used (refer to Figure 21).



**detailed description (continued)**

#### **command period**

After the rising edge of FS (FS triggers the operation) or the falling edge of  $\overline{CS}$  ( $\overline{CS}$  triggers the operation), SDI, SDO, and SCLK are enabled. The first four SCLK clocks form the command period. The four MSBs of input data, ID[15:12], are shifted in and decoded. These bits represent one of the 4-bit commands from the host, which defines the required operation (see Table 1, Command Set). The four MSBs of output, OD[15:12], are also shifted out via SDO during this period.

The commands are SELECT/CONVERSION, WRITE CFR, FIFO READ, SW POWER DOWN, and HARDWARE DEFAULT mode. The SELECT/CONVERSION command includes SELECT ANALOG INPUT and SELECT TEST commands. All cause a select/conversion operation. They select the analog signal being converted, and start the sampling/conversion process after the selection. WRITE CFR causes the configuration operation, which writes the device configuration information into the CFR register. FIFO READ reads the contents in the FIFO. SW POWER DOWN puts the device into software power-down mode to save power. Hardware default mode sets the device into the hardware default mode.

After the command period, the remaining 12 bits of SDI are written into the CFR register to configure the device if the command is WRITE CFR. Otherwise, these bits are ignored. The configuration is retained in the autopower-down and software power-down state. If SCLK stops (while CS remains low) after the first eight bits are entered, the next eight bits can be entered after SCLK resumes. The data on SDI are ignored after the 4-bit counter counts to 16 (falling edge of SCLK) or the low-to-high transition of  $\overline{CS}$ , whichever happens first.

The remaining 12 bits of output data are shifted out from SDO if the command is SELECT/CONVERSION or FIFO READ. Otherwise, the data on SDO are ignored. In any case, SDO goes into a high-impedance state after the 4-bit counter counts to 16 (falling edge of SCLK) or the low-to-high transition of CS, whichever happens first.



#### **Table 1. Command Set (CMR)**

NOTES: 9. REFP is external reference if external reference is selected, or internal reference if internal reference is programmed.

10. The output  $code = mid-scale code + zero offset error + gain error$ .

11. The output code = zero scale code + zero offset error.

12. The output  $code = full-scale code + gain error$ .



# **TLC3544, TLC3548 5-V ANALOG, 3-/5-V DIGITAL, 14-BIT, 200-KSPS, 4-/8-CHANNELS SERIAL ANALOG-TO-DIGITAL CONVERTERS WITH 0-5 V (PSEUDODIFFERENTIAL) INPUTS**

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#### **detailed description (continued)**

#### **Table 2. Configuration Register (CFR) Bit Definition**



#### **sampling period**

The sampling period follows the command period. The selected signal is sampled during this time. The device has three different sampling modes: normal short mode, normal long mode, and extended mode.

**Normal Short Sampling Mode:** Sampling time is controlled by SCLK. It takes 12 SCLK periods. At the end of sampling, the converter automatically starts the conversion period. After configuration, normal sampling, except FIFO READ and WRITE CFR commands, starts automatically after the fourth falling edge of SCLK that follows the falling edge of  $\overline{CS}$  if  $\overline{CS}$  triggers the operation, or follows the rising edge of FS if FS initiates the operation.



**sampling period (continued)**

**Normal Long Sampling Mode:** This mode is the same as normal short sampling, except that it lasts 44 SCLK periods.

**Extended Sampling Mode:** The external trigger signal, CSTART, triggers sampling and conversion. SCLK is not used for sampling. SCLK is also not needed for conversion if the internal conversion clock is selected. The falling edge of CSTART begins the sampling of the selected analog input. The sampling continues while CSTART is low. The rising edge of CSTART ends the sampling and starts the conversion (with about 15 ns internal delay). The occurrence of  $\overline{\text{CSTART}}$  is independent of the SCLK clock,  $\overline{\text{CS}}$ , and FS. However, the first CSTART cannot occur before the rising edge of the 11th SCLK. In other words, the falling edge of the first CSTART can happen at or after the rising edge of the 11th SCLK, but not before. The device enters the extended sampling mode at the falling edge of CSTART and exits this mode once CSTART goes to high followed by two consecutive falling edges of CS or two consecutive rising edges of FS (such as one read data operation followed by a write CFR). The first CS or FS does not cause conversion. Extended mode is used when a fast SCLK is not suitable for sampling, or when an extended sampling period is needed to accommodate different input signal source impedance.

#### **conversion period**

The conversion period is the third portion of the operation cycle. It begins after the falling edge of the 16th SCLK for normal short sampling mode, or after the falling edge of the 48th SCLK for normal long sampling, or on the rising edge of CSTART (with 15 ns internal delay) for extended sampling mode.

The conversion takes 18 conversion clocks plus 15 ns. The conversion clock source can be an internal oscillator, OSC, or an external clock, SCLK. The conversion clock is equal to the internal OSC if the internal clock is used, or equal to SCLK/4 when the external clock is programmed. To avoid premature termination of the conversion, enough time for the conversion must be allowed between consecutive triggers. EOC goes low at the beginning of the conversion period and goes high at the end of the conversion period. INT goes low at the end of this period.

#### **conversion mode**

Four different conversion modes (mode 00, 01, 10, 11) are available. The operation of each mode is slightly different, depending on how the converter samples and what host interface is used. Do not mix different types of triggers throughout the repeat or sweep operations.

**One Shot Mode (Mode 00):** Each operation cycle performs one sampling and one conversion for the selected channel. The FIFO is not used. When EOC is selected, it is generated while the conversion period is in progress. Otherwise,  $\overline{\text{INT}}$  is generated after the conversion is done. The result is output through the SDO pin during the next select/conversion operation.

**Repeat Mode (Mode 01):** Each operation cycle performs multiple samplings and conversions for a fixed channel selected according to the 4-bit command. The results are stored in the FIFO. The number of samples to be taken is equal to the FIFO threshold programmed via D[1:0] in the CFR register. Once the threshold is reached,  $\overline{\text{INT}}$  is generated, and the operation ends. If the FIFO is not read after the conversions, the data are replaced in the next operation. The operation of this mode starts with the WRITE CFR command to set conversion mode 01, then the SELECT/CONVERSION command, followed by a number of samplings and conversions of the fixed channel (triggered by CS, FS, or CSTART) until the FIFO threshold is hit. If CS or FS triggers the sampling, the data on SDI must be any one of the SELECT CHANNEL commands. This data is a dummy code for setting the converter in the conversion state. It does not change the existing channel selection set at the start of the operation until the FIFO is full. After the operation finishes, the host can read the FIFO, then reselect the channel and start the next REPEAT operation again; or immediately reselect the channel and start the next REPEAT operation (by issuing  $\overline{CS}$ , FS, or  $\overline{CSTAR}$ ), or reconfigure the converter and then start a new operation according to the new setting. If CSTART triggers the sampling, the host can also immediately start the next REPEAT (on the current channel) after the FIFO is full. Besides, if FS initiates the operation and CSTART triggers the sampling and conversions, CS must not toggle during the conversion. This mode allows the host to set up the converter, continue monitoring a fixed input, and to get a set of samples as needed.



#### **conversion mode (continued)**

**Sweep Mode (Mode 10):** During each operation, all of the channels listed in the sweep sequence (D[4:3] of the CFR register) are sampled and converted at one time according to the programmed sequence. The results are stored in the FIFO. When the FIFO threshold is reached, an interrupt  $(\overline{INT})$  is generated, and the operation ends. If the FIFO threshold is reached before all of the listed channels are visited, the remaining channels are ignored. This allows the host to change the sweep sequence length. The mode 10 operation starts with the WRITE CFR command to set the sweep sequence. The following triggers (CS, FS, or CSTART, depending on the interface) start the samplings and conversions of the listed channels in sequence until the FIFO threshold is hit. If  $\overline{\text{CS}}$  or FS starts the sampling, the SDI data must be any one of the SELECT commands to set the converter in the conversion state. However, this command is a dummy code. It does not change the existing conversion sequence. After the FIFO is full, the converter waits for the FIFO READ. It does nothing before the FIFO READ or the WRITE CFR command is issued. The host must read the FIFO completely or write the CFR. If CSTART triggers the samplings, the host must issue an extra SELECT/CONVERSION command (select any channel) via CS or FS after the FIFO READ or WRITE CFR. This extra period is named the arm period and is used to set the converter into the conversion state, but does not affect the existing conversion sequence. Besides, if FS initiates the operation and  $\overline{\text{CSTAT}}$  triggers the sampling and conversions,  $\overline{\text{CS}}$  must not toggle during the conversion.

**Repeat Sweep Mode (Mode 11):** This mode works in the same way as mode 10, except that it is not necessary to read the FIFO before the next operation after the FIFO threshold is hit. The next SWEEP can repeat immediately, but the contents in the FIFO are replaced by the new results. The host can read the FIFO completely, then issue the next SWEEP or repeat the SWEEP immediately (with the existing sweep sequence) by issuing sampling/conversion triggers ( $\overline{\text{CS}}$ , FS or  $\overline{\text{CSTART}}$ ) or change the device setting with the WRITE CFR.

The memory effect of charge redistribution DAC exists when the mux switches from one channel to another. This degrades the channel-to-channel isolation if the channel changes after each conversion. For example, in mode 10 and 11, the isolation is about 70 dB for the sweep sequence 0-1-2-3-4 (refer to Figure 8). The memory effect can be reduced by increasing the sampling time or using the sweep sequence 0-0-2-2-4-4-6-6 and ignoring the first sample of each channel. Figure 8 shows the typical isolation vs throughput rate when applying a sine signal (35 kHz, 3.5 V<sub>p-p</sub>) on CH0 and dc on CH1 converting both channels alternately and measuring the attenuation of the sine wave in CH1.



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# **TLC3544, TLC3548 5-V ANALOG, 3-/5-V DIGITAL, 14-BIT, 200-KSPS, 4-/8-CHANNELS SERIAL ANALOG-TO-DIGITAL CONVERTERS WITH 0-5 V (PSEUDODIFFERENTIAL) INPUTS**

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#### **operation cycle timing**



† Non JEDEC terms used.

After the operation is finished, the host has several choices. Table 3 summarizes operation options.



#### **operation cycle timing (continued)**

# **Table 3. Operation Options**



#### **operation timing diagrams**

The FIFO read and write CFR are nonconversion operations. The conversion operation performs one of four types of conversion: mode 00, 01, 10, and 11

Write Cycle (WRITE CFR Command): Write cycle does not generate EOC or INT, nor does it carry out any conversion.



**Figure 9. Write Cycle, FS Initiates Operation**



#### **operation timing diagrams (continued)**



**FIFO Read Operation:** When the FIFO is used, the first command after INT is generated is assumed to be the FIFO read. The first FIFO content is sent out immediately before the command is decoded. If this command is not a FIFO read, the output is terminated. Using more layers of the FIFO reduces the time taken to read multiple conversion results, because the read cycle does not generate an EOC or INT, nor does it make a data conversion. Once the FIFO is read, the entire contents in the FIFO must be read out. Otherwise, the remaining data is lost.



**Figure 11. FIFO Read Cycle, CS Initiates Operation, FS = 1**



**conversion operation**



**Figure 13. Mode 00, FS Initiates Operation**



#### **conversion operation (continued)**



**Figure 16. Mode 01, CSTART Triggers Samplings/Conversions**



#### **conversion operation (continued)**



**Figure 19. Mode 11, CS Initiates Operations**



#### **conversion operation (continued)**



# **Figure 20. Mode 11, CSTART Triggers Samplings/Conversions**

#### **conversion clock and conversion speed**

The conversion clock source can be the internal OSC, or the external clock SCLK. When the external clock is used, the conversion clock is equal to SCLK/4. It takes 18 conversion clocks plus 15 ns to finish the conversion. If the external clock is selected, the conversion time (not including sampling time) is  $18X(4/f_{\rm SCLK})+15$  ns. Table 4 shows the maximum conversion rate (including sampling time) when the analog input source resistor is 1 kΩ.



#### **Table 4. Maximum Conversion Rate**

#### **FIFO operation**



**FIFO Threshold Pointer**





### **FIFO operation (continued)**

The device has an 8-level FIFO that can be programmed for different thresholds. An interrupt is sent to the host after the preprogrammed threshold is reached. The FIFO is used to store conversion results in mode 01, 10, and 11, from either a fixed channel or a series of channels according to a preprogrammed sweep sequence. For example, an application may require eight measurements from channel 3. In this case, if the threshold is set to full, the FIFO is filled with 8 data conversions sequentially taken from channel 3. Another application may require data from channel 0, 2, 4, and 6 in that order. The threshold is set to 1/2 full and sweep sequence is selected as 0–2–4–6–0–2–4–6. An interrupt is sent to the host as soon as all four data conversions are in the FIFO. The FIFO is reset after a power on and a WRITE CFR operation. The contents of the FIFO are retained during autopower down and software power down.

**Powerdown:** The device has two power-down modes.

**AutoPower-Down Mode:** The device enters the autopower-down state at the end of a conversion.

In autopower-down, the power consumption reduces to about 1.8 mA when an internal reference is selected. The built-in reference is still on to allow the device to resume quickly. The resumption is fast enough for use between cycles. An active CS, FS, or CSTART resumes the device from power-down state. The power current is 20 µA when an external reference is programmed and SCLK stops.

**Software Power-Down Mode:** Writing 8000h to the device puts the device into the software power-down state, and the entire chip (including the built-in reference) is powered down. The power current is reduced to about 20  $\mu$ A if SCLK stops. Deselect  $\overline{\text{CS}}$  to save power once the device is in the software power-down mode. An active CS, FS, or CSTART restores the device. There is no time delay when an external reference is selected. However, if an internal reference is used, it takes about 20 ms to warm up.

The configuration register is not affected by any of the power-down modes but the sweep operation sequence must be started over again. All FIFO contents are retained in both power-down modes.



# **TYPICAL CHARACTERISTICS**







**Figure 23**



# **TLC3544, TLC3548 5-V ANALOG, 3-/5-V DIGITAL, 14-BIT, 200-KSPS, 4-/8-CHANNELS SERIAL ANALOG-TO-DIGITAL CONVERTERS WITH 0-5 V (PSEUDODIFFERENTIAL) INPUTS**

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# **TYPICAL CHARACTERISTICS**

**Figure 26**



# **TYPICAL CHARACTERISTICS**





# **TYPICAL CHARACTERISTICS**





# **APPLICATION INFORMATION**

### **interface with host**

Figure 34 shows examples of the interface between a single converter and a host DSP (TMS320C54x™ DSP) or microprocessor. The C54x is set as FWID = 1 (active pulse width = 1CLK),  $(R/X)$  DATDLY = 1 (1 bit data delay),  $CLK(X/R)P = 0$  (transmit data are clocked out at rising edge of  $CLK$ , receive data are sampled on falling edge of CLK), and FS( $X/R$ )P = 1 (FS is active high). If multiple converters connect to the same C54x, use  $\overline{CS}$  as the chip select.

The host microprocessor is set as the SPI master with CPOL =  $0$  (active high clock), and CPHA = 1 (transmit data is clock out at rising edge of CLK, receive data are sampled at falling edge of CLK). 16 bits (or more) per transfer is required.



**Figure 34. Typical Interface to Host DSP and Microprocessor**

# **sampling time analysis**

Figure 35 shows the equivalent analog input circuit of the converter. During the sampling, the input capacitor,  $C_i$ , has to be charged to V<sub>C</sub>, (V<sub>C</sub> = V<sub>s</sub>  $\pm$  voltage of 1/4 LSB = V<sub>s</sub>  $\pm$  [V<sub>s</sub>/65532] for 14 bit converter).

$$
t_{(s)} = R_t \times C_i \times \text{In (65532) where } R_t = R_s + r_i, t_{(s)} = \text{Sampling time}
$$





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**MENTS** 

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#### **TAPE DIMENSIONS**





#### TAPE AND REEL INFORMATION

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\*All dimensions are nominal



DW (R-PDSO-G20)

PLASTIC SMALL OUTLINE



NOTES: A. All linear dimensions are in inches (millimeters). Dimensioning and tolerancing per ASME Y14.5M-1994.

B. This drawing is subject to change without notice.

C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15).

D. Falls within JEDEC MS-013 variation AC.



# **LAND PATTERN DATA**



NOTES:

- All linear dimensions are in millimeters. А.
- B. This drawing is subject to change without notice.
- C. Refer to IPC7351 for alternate board design.
- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525
- Ε. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.



 $DW (R-PDSO-G24)$ 

PLASTIC SMALL OUTLINE



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B. This drawing is subject to change without notice.

C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15).

D. Falls within JEDEC MS-013 variation AD.



PW (R-PDSO-G20)

PLASTIC SMALL OUTLINE



This drawing is subject to change without notice. **B.** 

 $\hat{\mathbb{C}}$  Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0,15 each side.

 $\hat{\mathbb{D}}$  Body width does not include interlead flash. Interlead flash shall not exceed 0,25 each side.

E. Falls within JEDEC MO-153



PW (R-PDSO-G24)

PLASTIC SMALL OUTLINE



А. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994. This drawing is subject to change without notice. **B.** 

 $\hat{\mathbb{C}}$  Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0,15 each side.

 $\hat{\mathbb{D}}$  Body width does not include interlead flash. Interlead flash shall not exceed 0,25 each side.

E. Falls within JEDEC MO-153



# **LAND PATTERN DATA**



NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
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- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525 for other stencil recommendations.
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